Service category 2.1.1

Calibration of local frequency standard by dual mixer time difference method

Basic information

- Quantity
- Instrument or artifact
- Instrument type or method
- Measurement level or range
- Measurement condition

frequency local frequency standard dual mixer time difference measurement 1 MHz to 20 MHz

0.9 V_{pp} to 4.5 V_{pp} with 50 Ω

Instrument used

• Dual mixer time difference system

Measurement setup



Figure 1. Measurement setup.

List of uncertainty

- 1. UTC uncertainty
- 2. UTC UTC(k) link uncertainty
- 3. UTC(k) prediction uncertainty
- 4. UTC(k) source uncertainty
- 5. Cable uncertainty
- 6. Measurement system noise uncertainty

Detail of uncertainty calculation

1. UTC uncertainty includes two parts: fractional deviation *d* and standard uncertainty *u* as described below

$$U_{UTC} = \sqrt{d^2 + u^2} = \sqrt{(5.2 \times 10^{-15})^2 + (0.3 \times 10^{-15})^2} = 5.2 \times 10^{-15}$$

- *d,* fractional deviation, 5.2E-15 (the worst value in previous year, as published on Circular T)
- *u,* standard uncertainty, 0.3E-15 (the worst value in previous year, as published on Circular T)
- 2. UTC-UTC(k) uncertainty

$$U_{link} = \frac{u_A}{86400*5} * \sqrt{2} = 1.3 \times 10^{-15}$$

- Uncertainty $u_A = 0.4$ ns (the worst value in previous year, as published on Circular T)
- 3. UTC(k) prediction uncertainty is comprised of two factors:
 - Average difference of UTC-UTC(k) from previous year data
 - Standard deviation of UTC-UTC(k) from previous year data

$$U_{UTC(k)} = \sqrt{average \ difference^2 + standard \ deviation^2}$$

= $\sqrt{(1.4 \times 10^{-16} \times \sqrt{5})^2 + (8.6 \times 10^{-15})^2} = 8.6 \times 10^{-15}$

- 4. UTC(k) source uncertainty
 - Stability of the master clock at one day time interval, $U_{UTC(k) \text{ source}} = 3.0 \times 10^{-15}$
- 5. Cable uncertainty

$$U_{cable} = \frac{0.001 n s^{0} C / m \times temperature \text{ var } aition \times cablelength}{43200 s} = 2.8 \times 10^{-15}$$

- The temperature coefficient $\Delta f/f = 0.001 \text{ ns/}^{\circ}\text{C/m}$, as measured in the lab using a temperature chamber
- The lab ambient condition is (23±2) °C
- The cable length is taken as 30 m
- 6. Measurement system noise uncertainty
 - The measurement system noise can be measured by the setup shown in Appendix A
 - The uncertainty *U*_{noise} is the stability of the measurement result at one day time interval

Uncertainty budget table

S/N	Uncertainty Source	Uncertainty Value	Туре	Distribution	Conversion factor K	Standard uncertainty (Hz/Hz)
1	U _{UTC}	5.2×10 ⁻¹⁵	A	normal	1	5.2×10 ⁻¹⁵
2	U _{link}	1.3×10 ⁻¹⁵	A	normal	1	1.3×10 ⁻¹⁵
3	U _{UTC(k)}	8.6 ×10 ⁻¹⁵	A	normal	1	8.6 ×10 ⁻¹⁵
4	U _{UTC(k)_} source	3.0×10 ⁻¹⁵	A	normal	1	3.0×10 ⁻¹⁵
5	U _{cable}	2.8×10 ⁻¹⁵	В	rectangular	√3	1.6×10 ⁻¹⁵
6	U _{noise}	2.0×10 ⁻¹⁶	A	normal	1	2.0×10 ⁻¹⁶
Combined Uncertainty = $\sqrt{U_{UTC}^2 + U_{link}^2 + U_{UTC(k)}^2 + U_{UTC(k)_source}^2 + U_{cable}^2 + U_{noise}^2} = 1.1 \times 10^{-14}$						
Expanded Uncertainty = $2 \times \sqrt{U_{UTC}^{2} + U_{link}^{2} + U_{UTC(k)}^{2} + U_{UTC(k)_{-}source}^{2} + U_{cable}^{2} + U_{noise}^{2}} = 2.2 \times 10^{-14}$						

The measurement system noise was measured with setup in Figure A1. The result is illustrated in Figure A2.



Figure A1. Measurement setup of system noise.



Figure A2. Frequency stability of system noise measurement.