

# Geodetic VLBI and its Perspectives

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## Contents

- **What is geodetic VLBI?**
- **How to get residual delay and delay rate from correlation data**
- **Measurements of plate motion and crustal deformation**
- **Evolution of VLBI system**
  - **direct sampling**
  - **Wideband bandwidth synthesis, etc.**
  - **VGOS (VLBI Global Observing System)**



# Space Geodetic Techniques

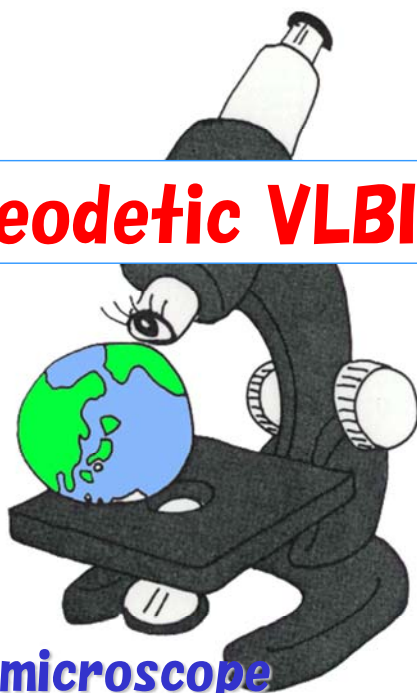
- **VLBI**  
(Very Long Baseline Interferometry)
- **GNSS (Global Navigation Satellite System)**
  - GPS (USA), GALILEO (EU), GLONASS (Russia), BeiDou (China), QZS (Japan), IRNSS (India)
- **SLR (Satellite Laser Ranging)**



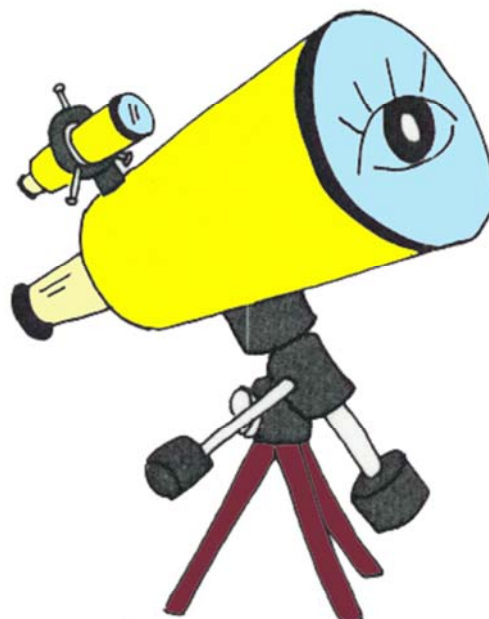
## VLBI can measure what?

two functions as a tool

**Geodetic VLBI**



microscope  
to investigate Earth

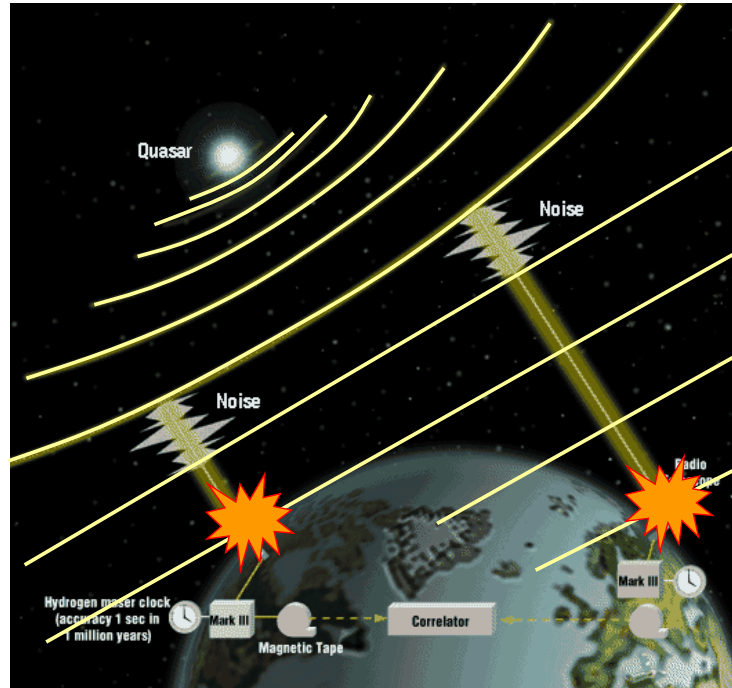


telescope  
to investigate space



# Measure Time Delay

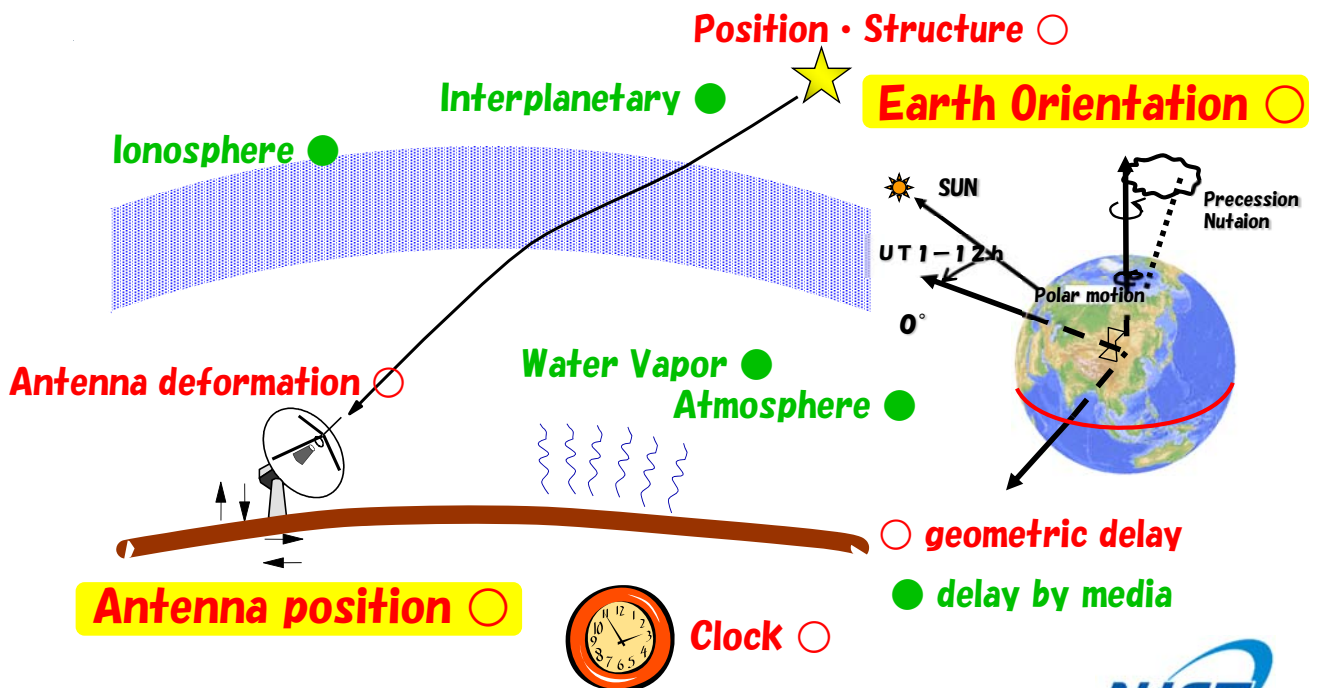
receive radio star signals at 2 stations




measure time delay



## Measured delay is affected by

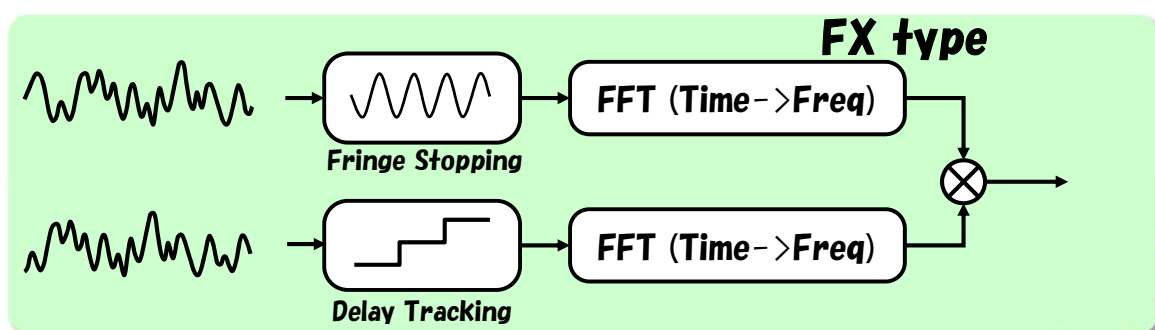
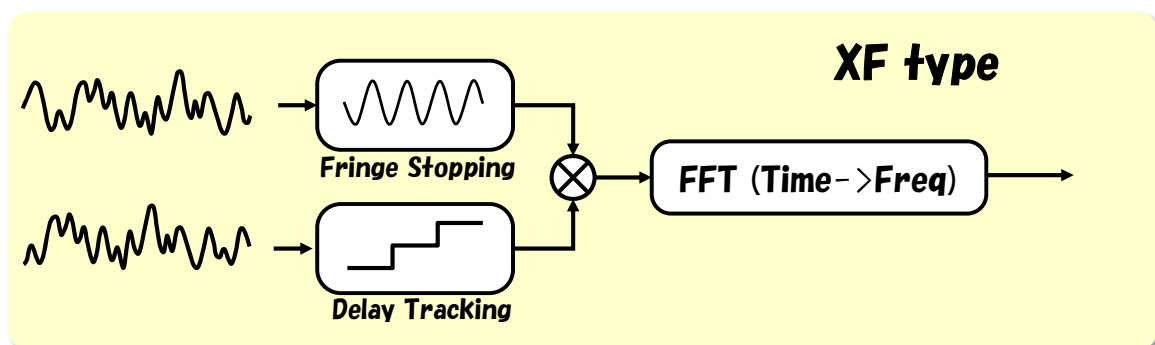


# How to get residual delay and delay rate

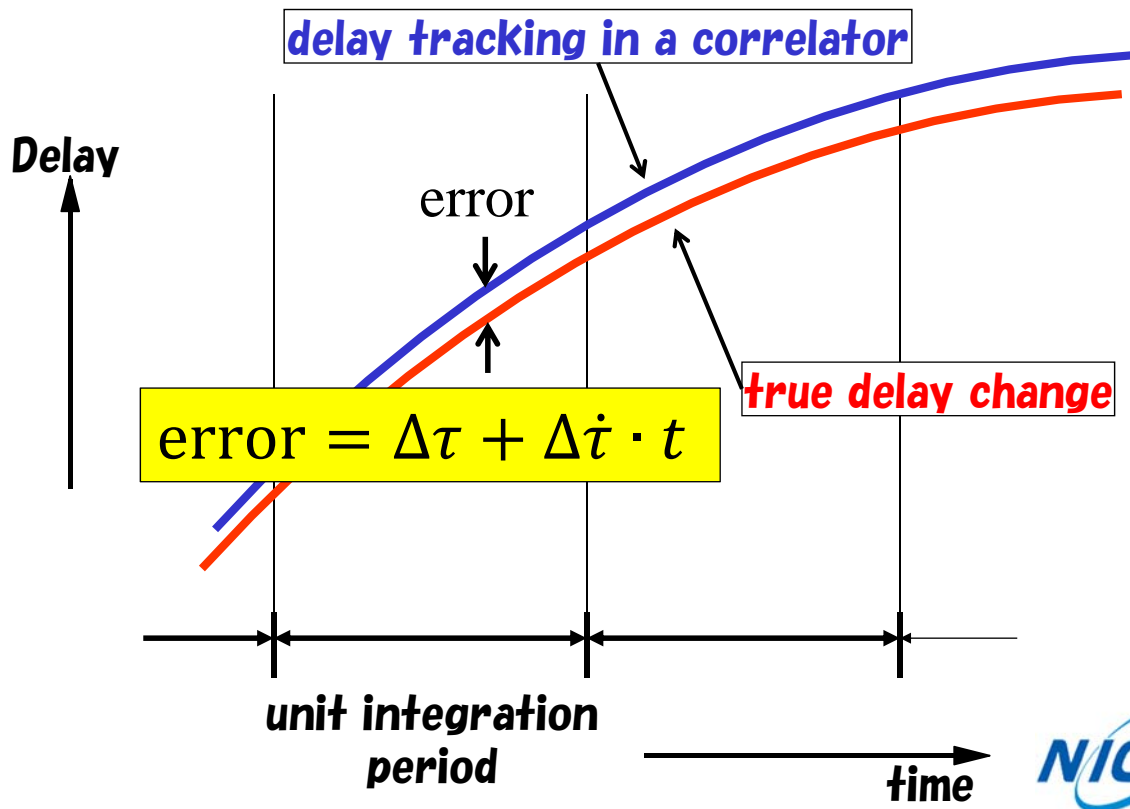


## Correlation Processing

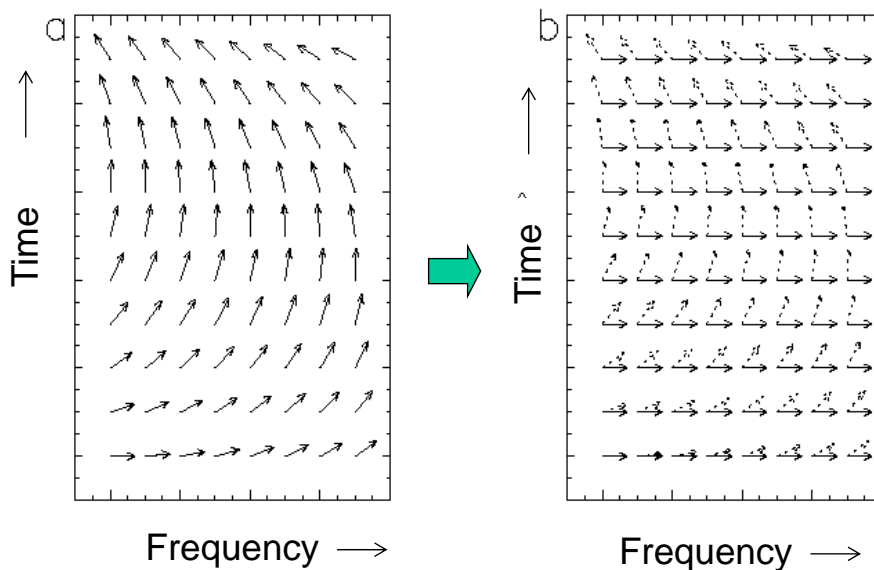
Two types of correlators



# residual delay $\Delta\tau$ and delay rate $\Delta\dot{\tau}$



## How to obtain residual delay $\Delta\tau$ and delay rate $\Delta\dot{\tau}$ from cross-spectra



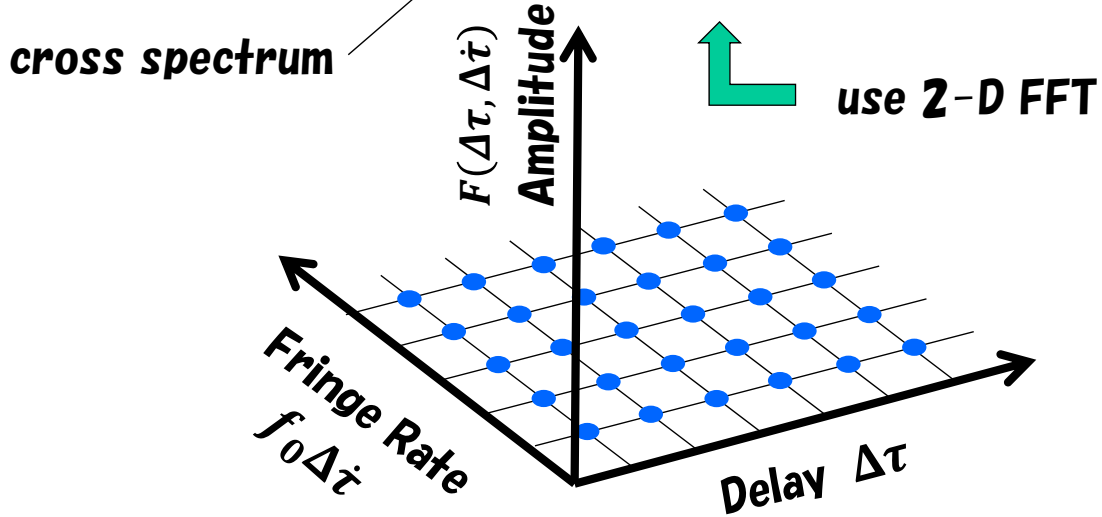
$\Delta\tau$  yields phase rotation on frequency domain

$\Delta\dot{\tau}$  yields phase rotation on time domain



# Search Function

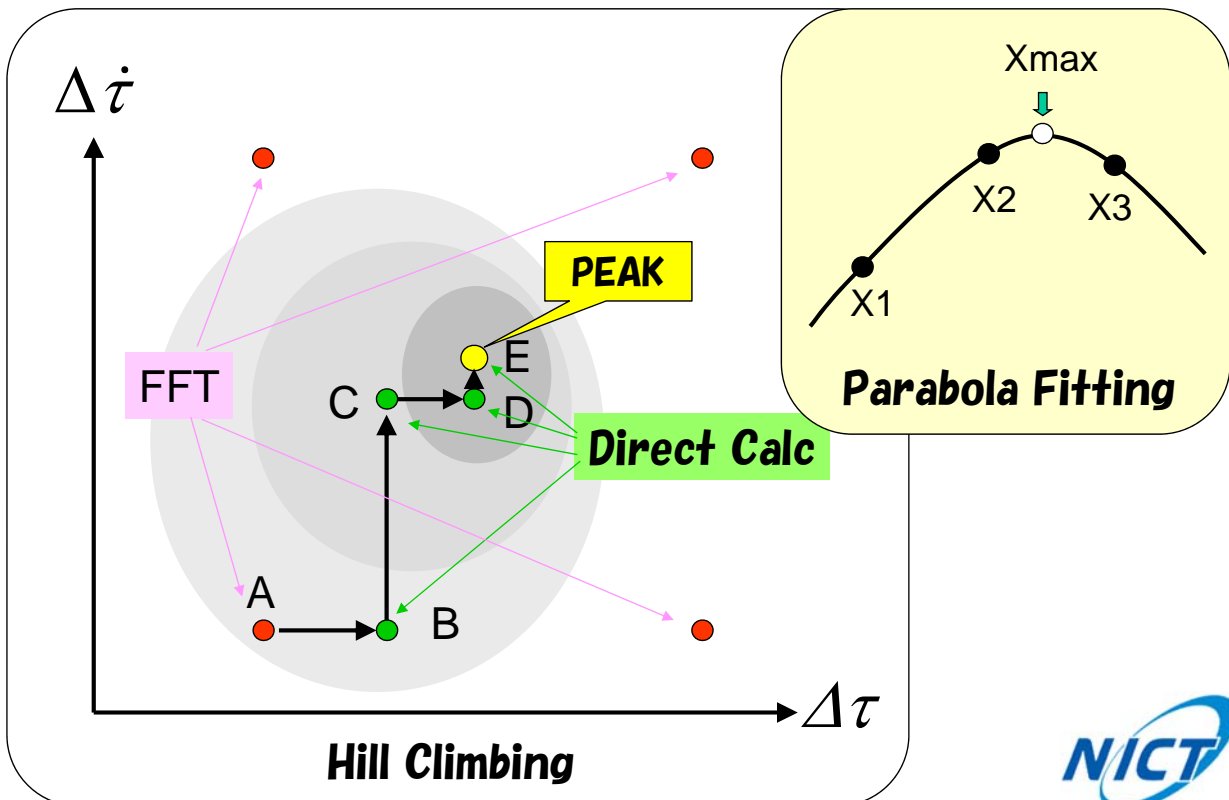
$$F(\Delta\tau, \Delta\dot{\tau}) = \left| \int_0^B \left\{ \int_0^T S(f, t) e^{-i2\pi f_0 \Delta\dot{\tau} t} dt \right\} e^{-i2\pi \Delta\tau f} df \right|$$



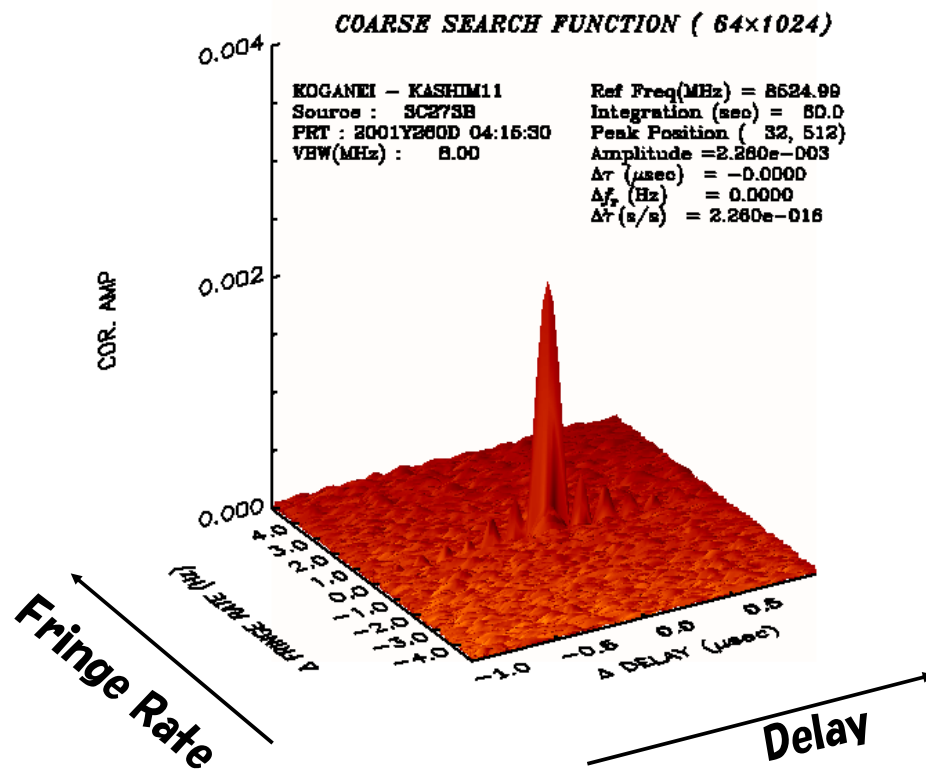
$f_0$  : reference RF frequency



## Hill climbing method and parabola fitting



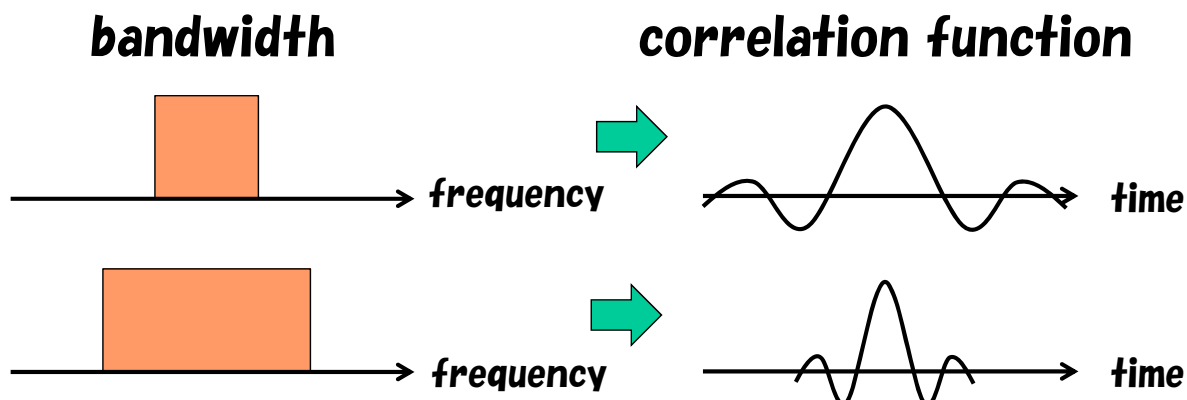
# Example of actual search function



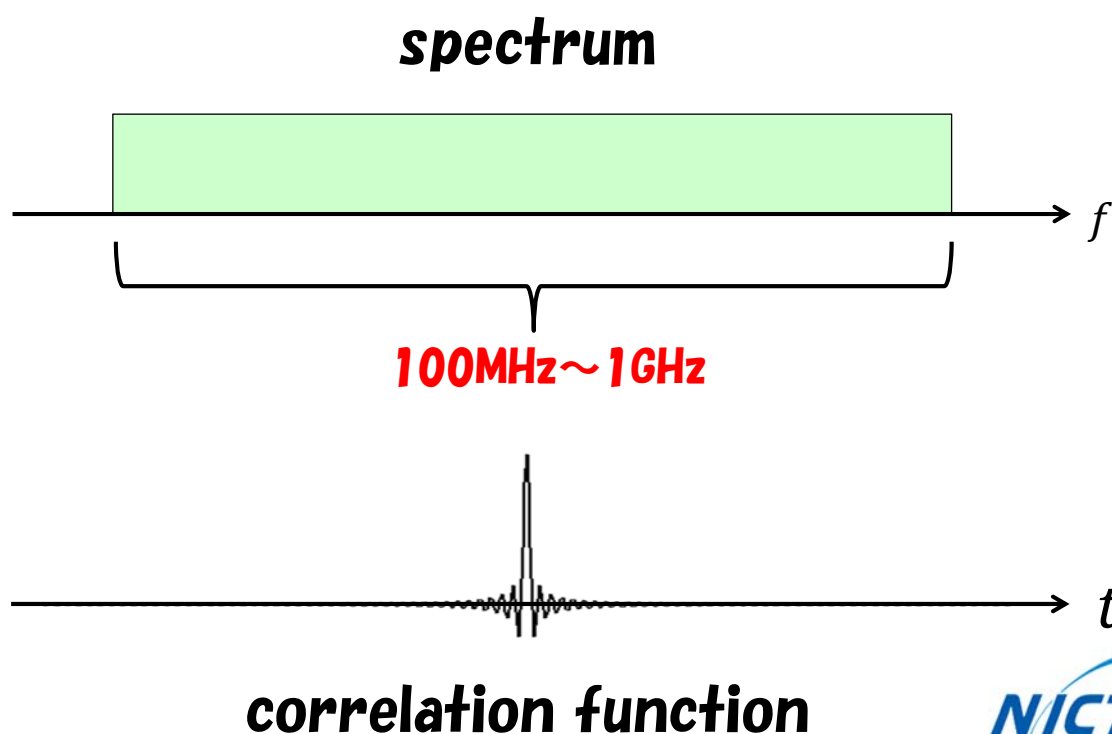
# Bandwidth Synthesis (BWS)



**delay resolution  $\propto 1/\text{bandwidth}$**

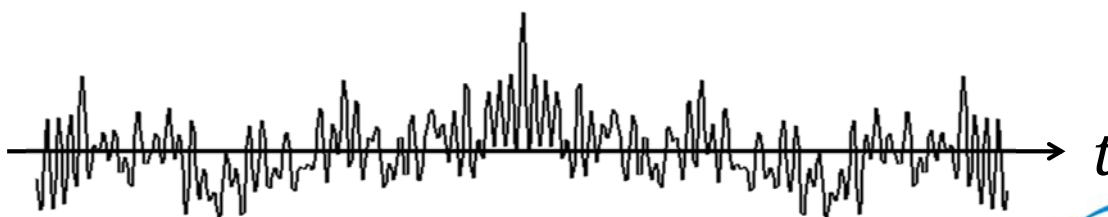
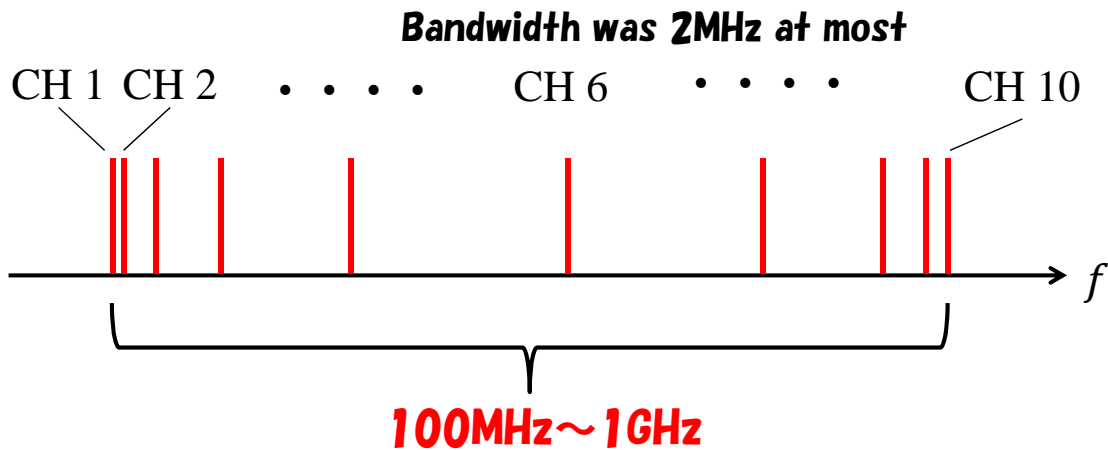


## **Conventional Bandwidth Synthesis**





# Conventional Bandwidth Synthesis



correlation function



## Search Function for BWS

$$F(\Delta\tau, \Delta\dot{\tau}) = \left| \int_0^B \left\{ \int_0^T \boxed{S(f, t)} e^{-i2\pi f_0 \Delta\dot{\tau} t} dt \right\} e^{-i2\pi \Delta\tau f} df \right|$$

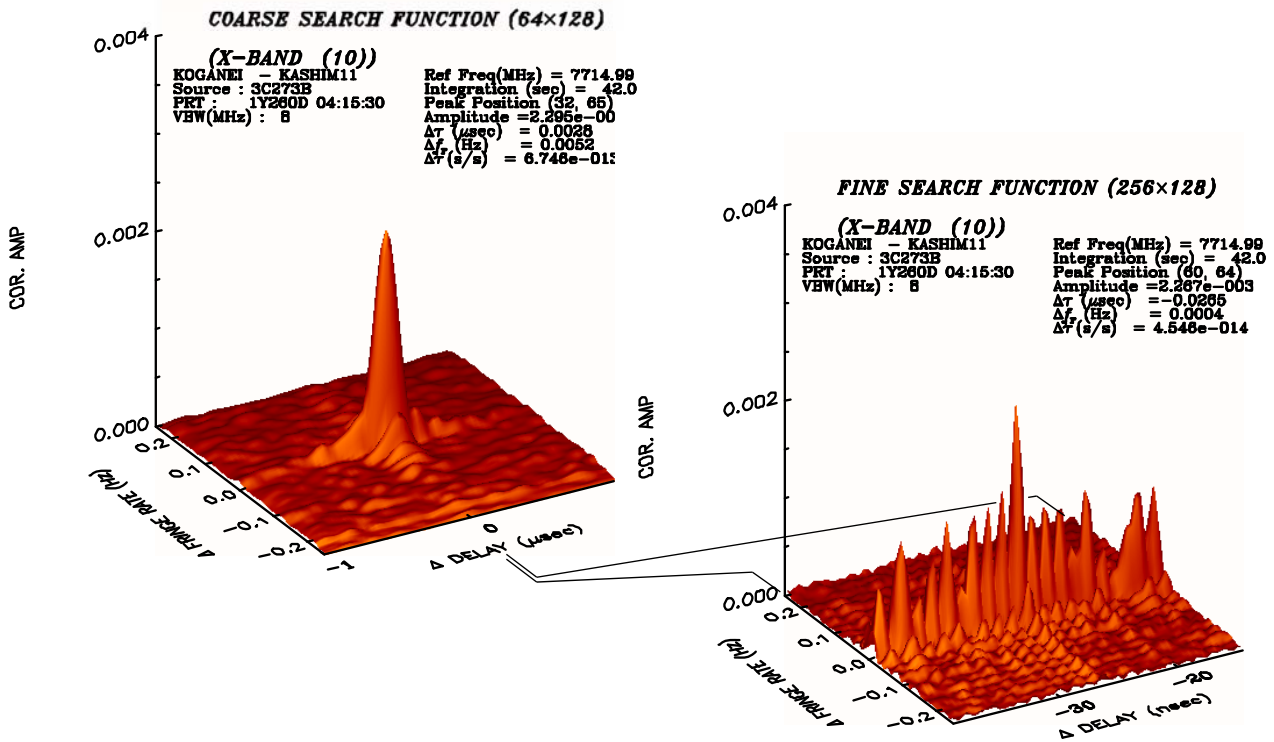
Now combined cross spectrum

**Each channel phase is compensated by using the phase of PCAL signal**

$f_0$  : reference RF frequency



# Improvement of Delay Resolution by Bandwidth Synthesis



## Antenna Motion during Geodetic VLBI



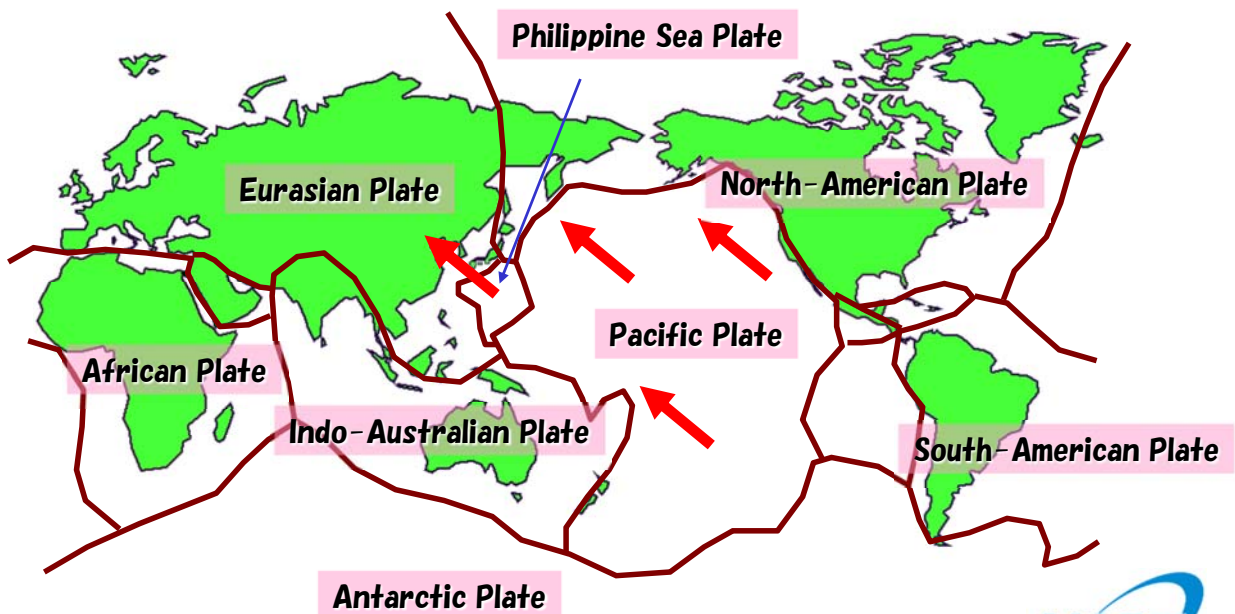
10sec  $\rightarrow$  1hrs    100~300 scans / 24 hours



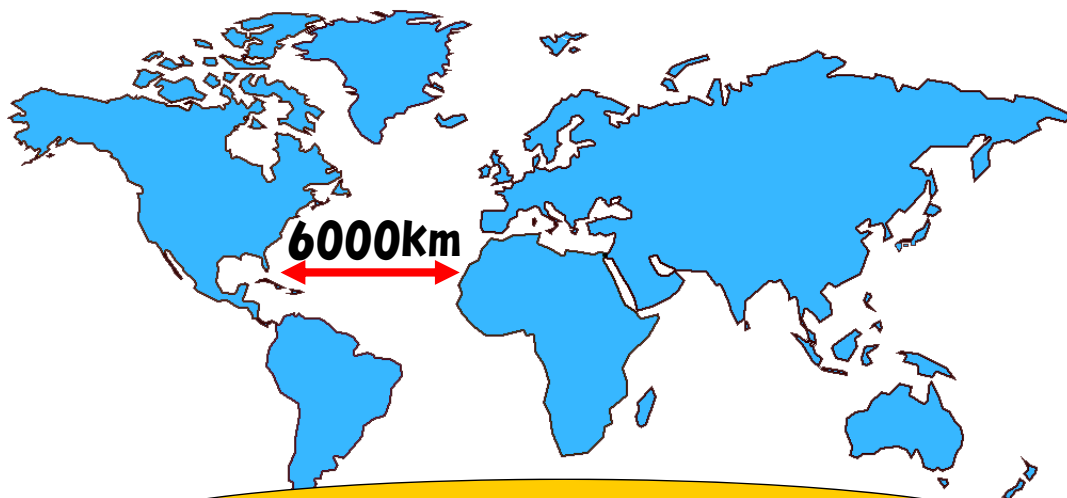
# First Target was Measurements of Plate Motion



## Tectonic Plates



# Estimation of Plate Motion



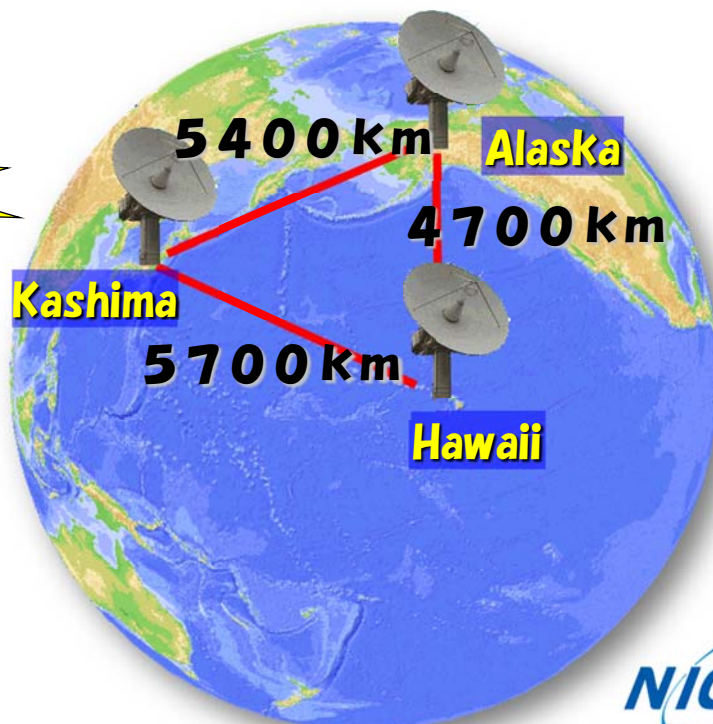
**Atlantic Ocean began to spread 50 Ma ago**

$$6000\text{km} / 50\text{Ma} = 12\text{cm/year}$$



## Crustal Dynamics Project (direct measurements of plate motion)

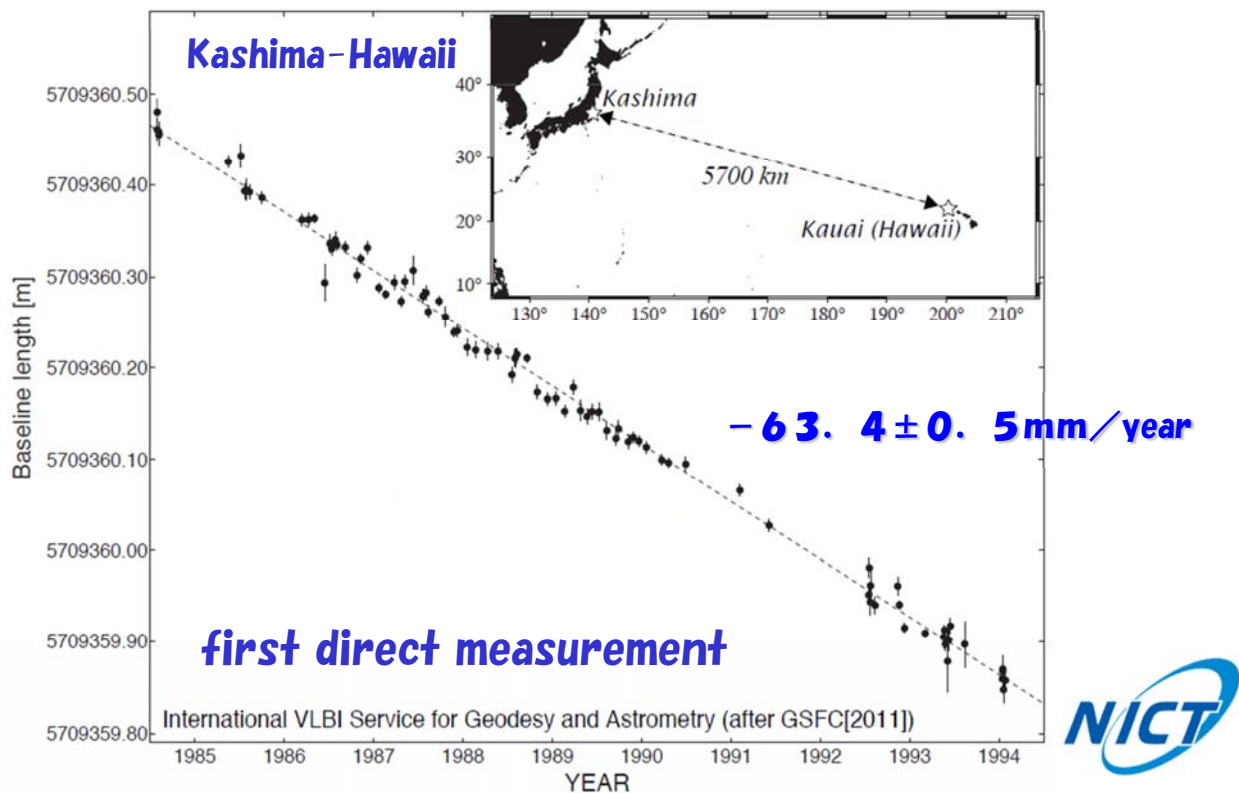
**start 1983**



**CDP was  
promoted by NASA**

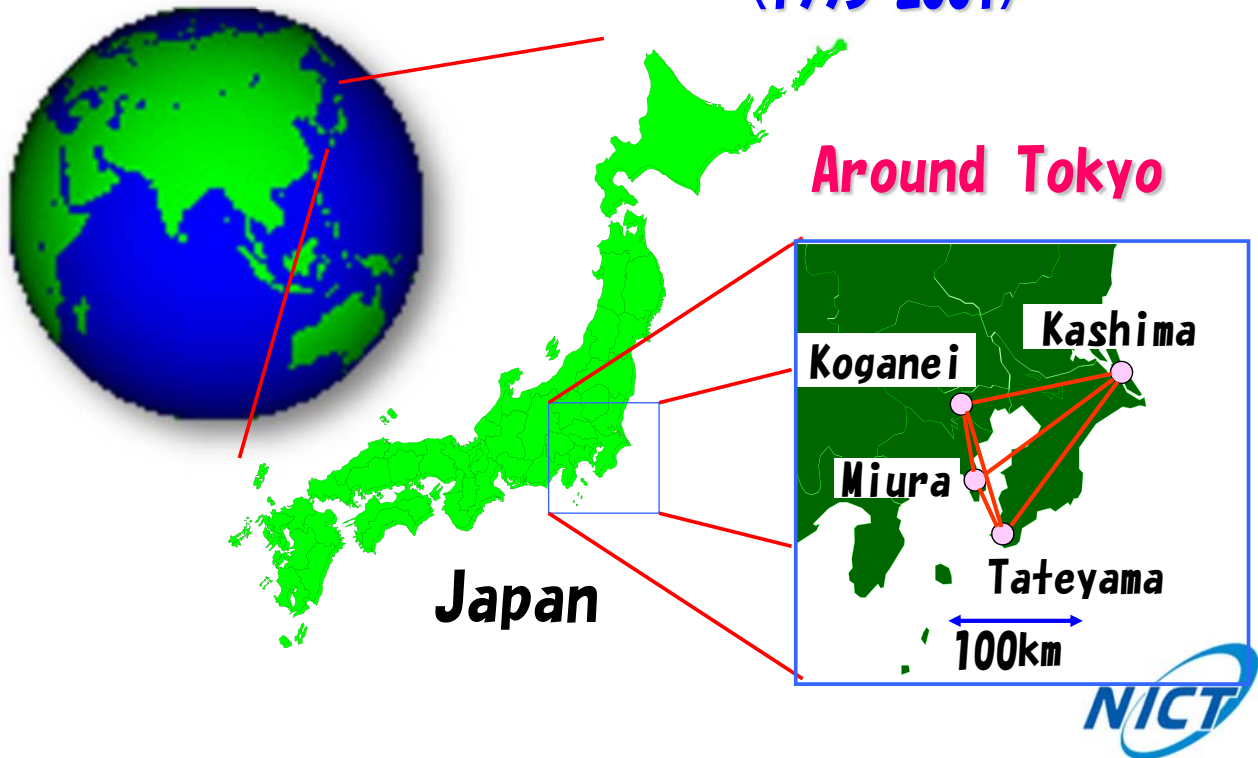


# Baseline length change measured on Kashima-Hawaii Baseline

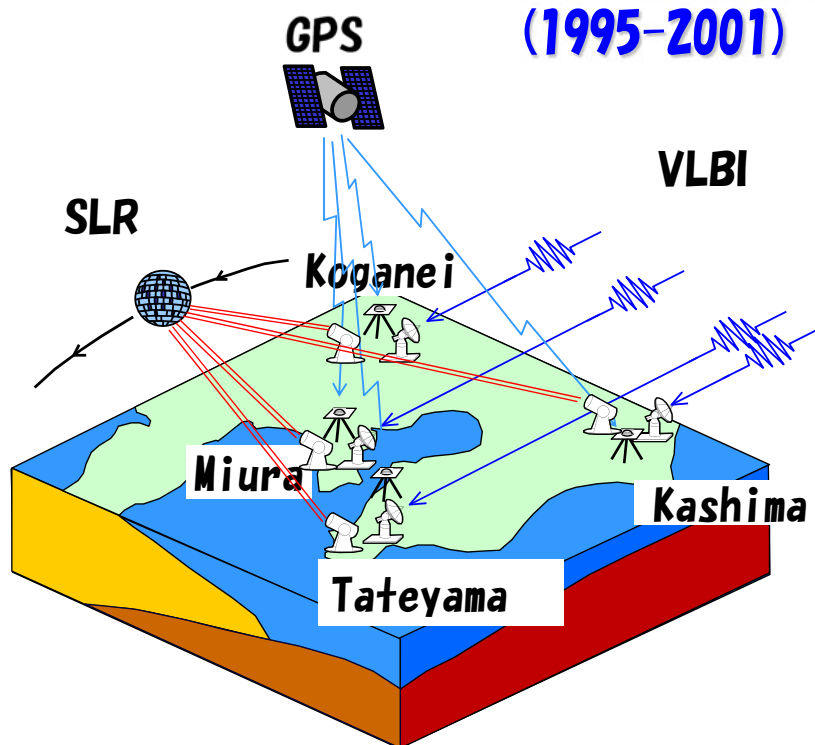


# Continuous Measurements of Crustal Deformation Around Tokyo (KSP Project)

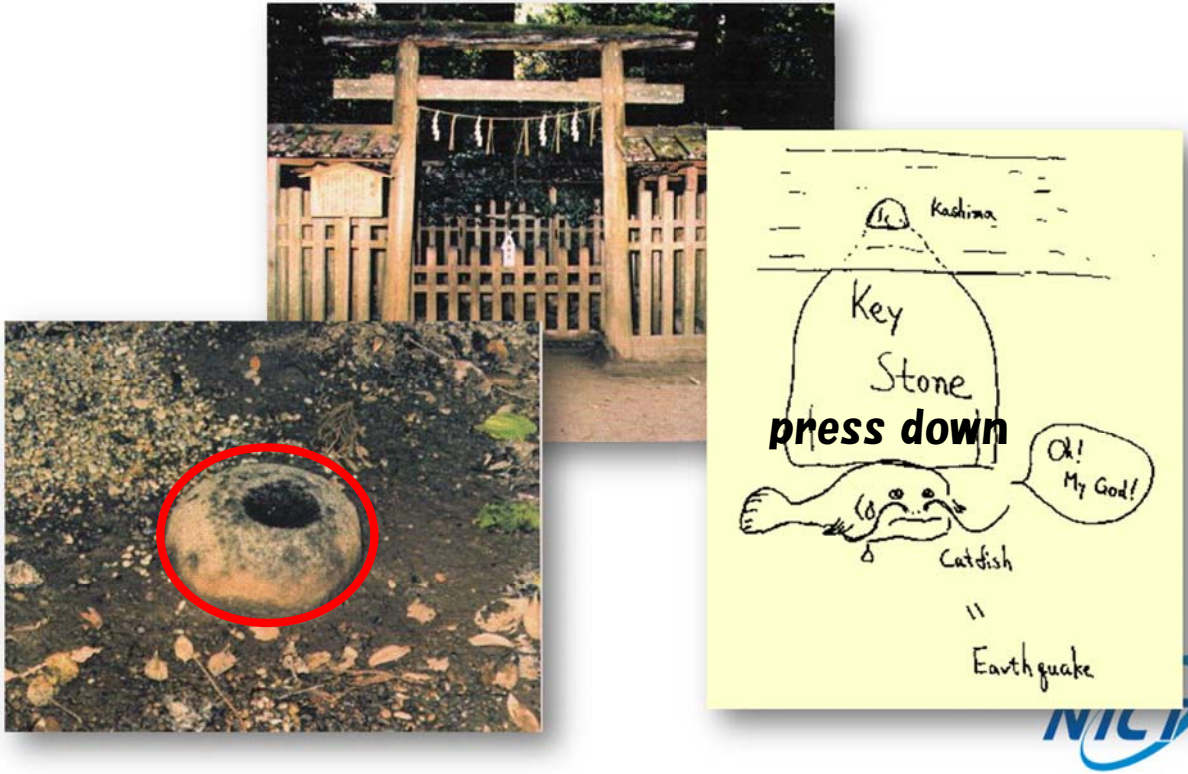
# KSP (Key Stone Project) (1995-2001)



# KSP (Key Stone Project) (1995-2001)



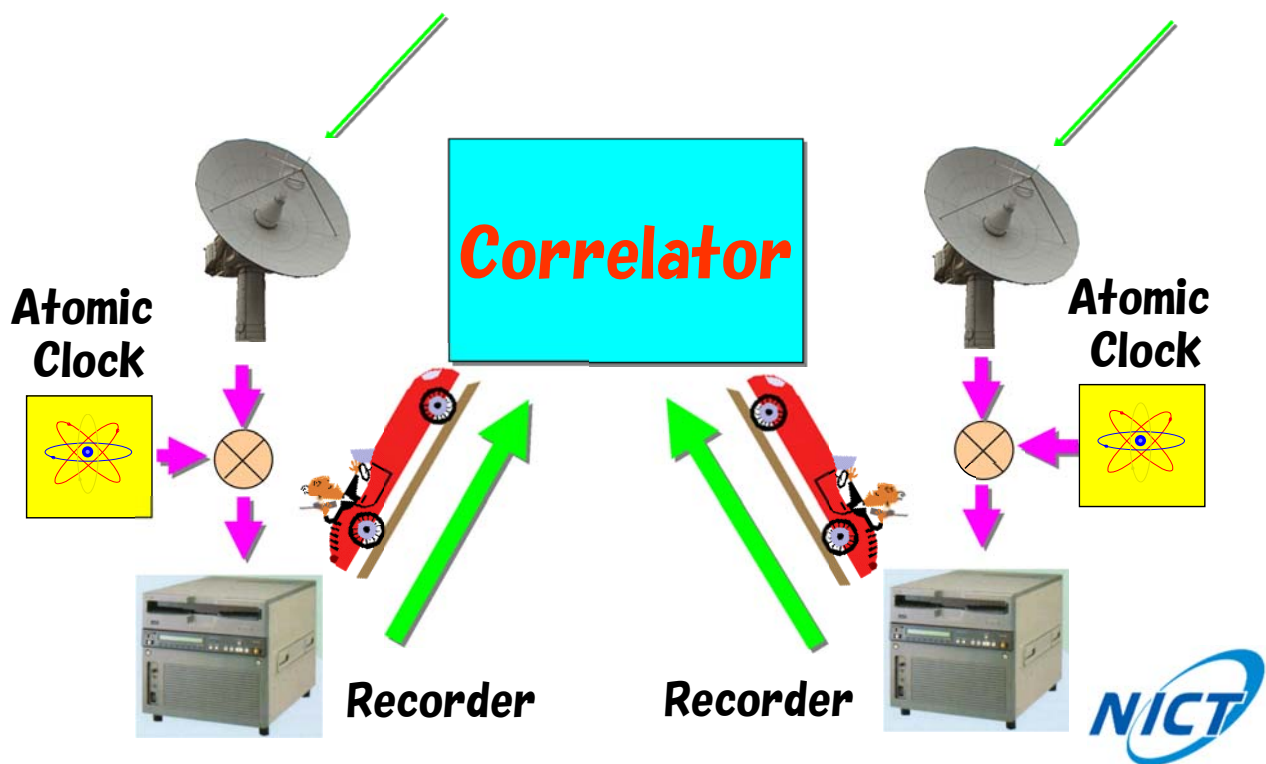
# Keystone at Kashima Jingu Shrine



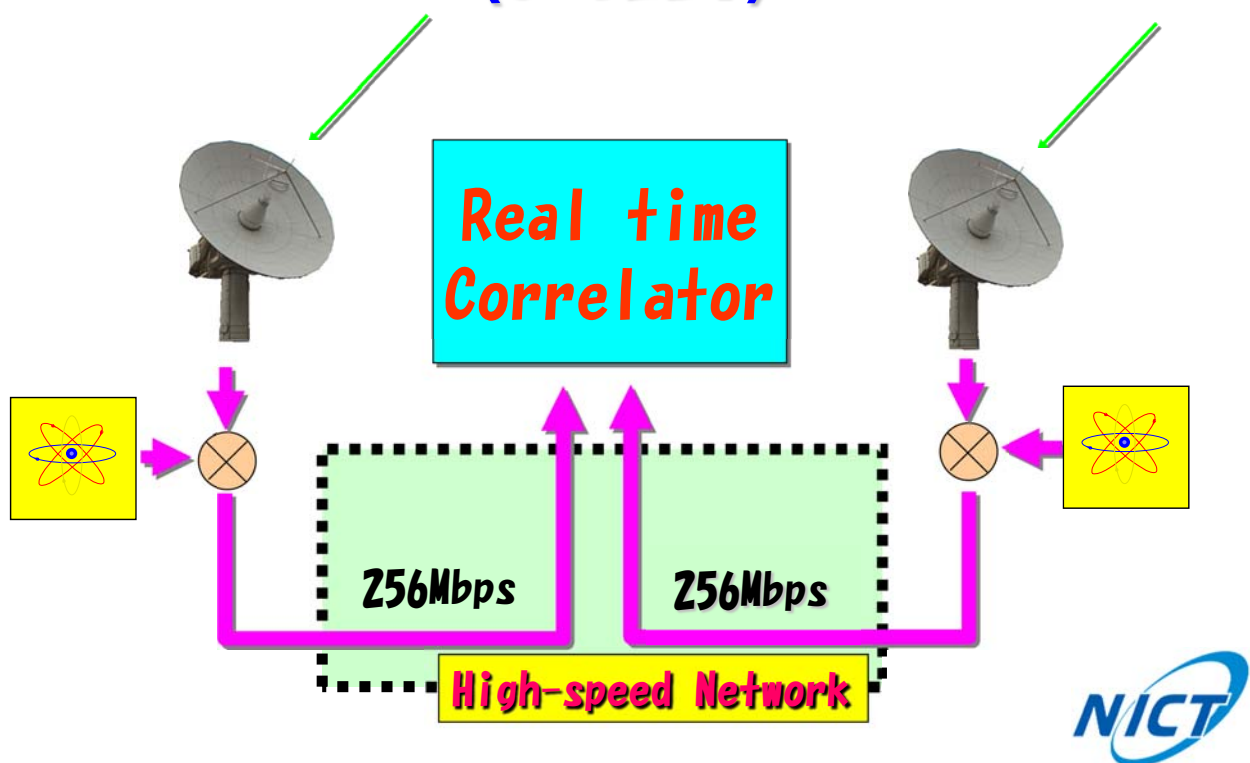
## Keystone Legend



# Conventional VLBI at that time

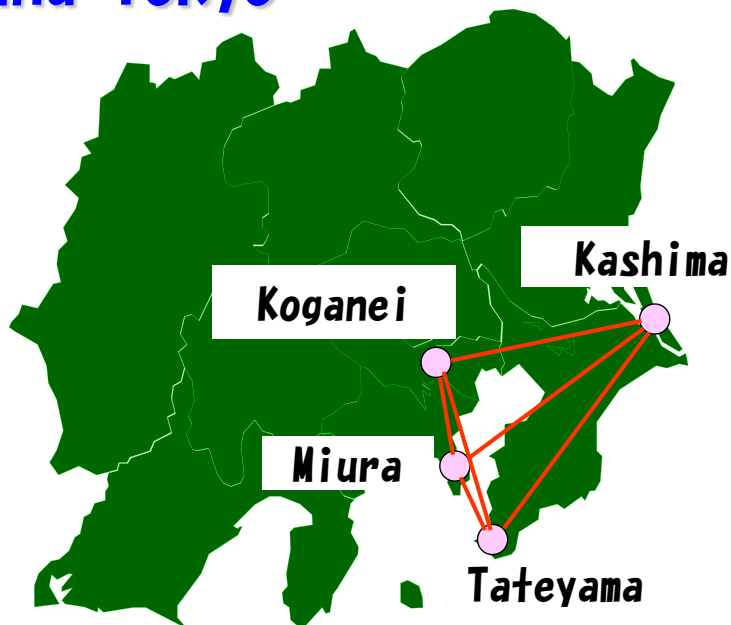


# Real Time VLBI (e-VLBI)





# Around Tokyo



June 26, 2000

Miyake Isl.

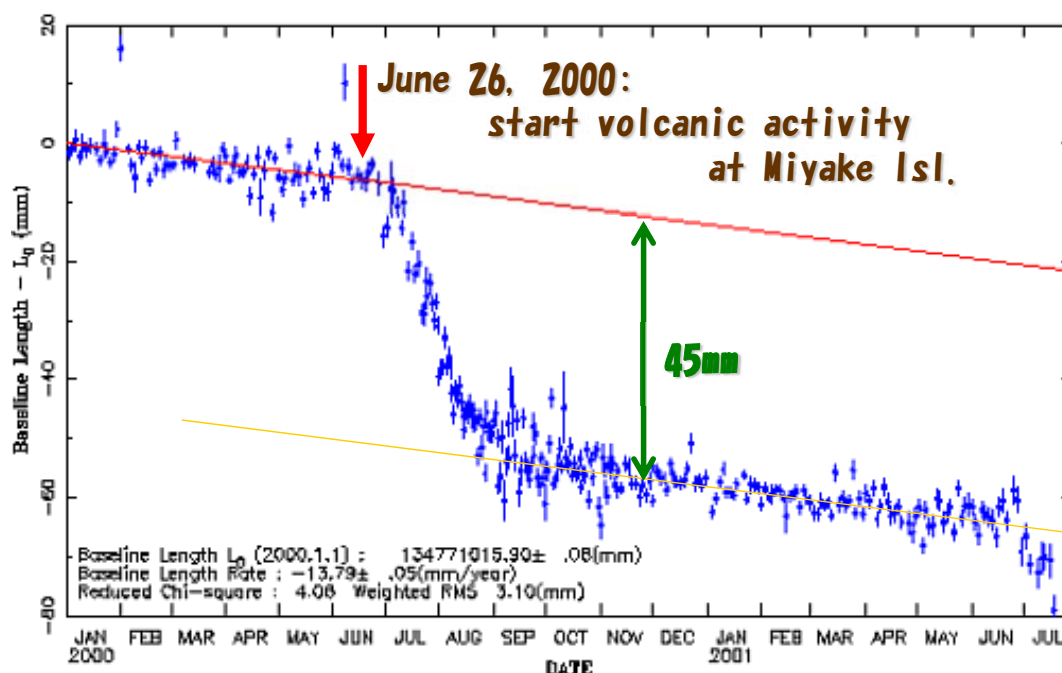
100km



# Kashima - Tateyama baseline

KASHIM11-TATEYAMA

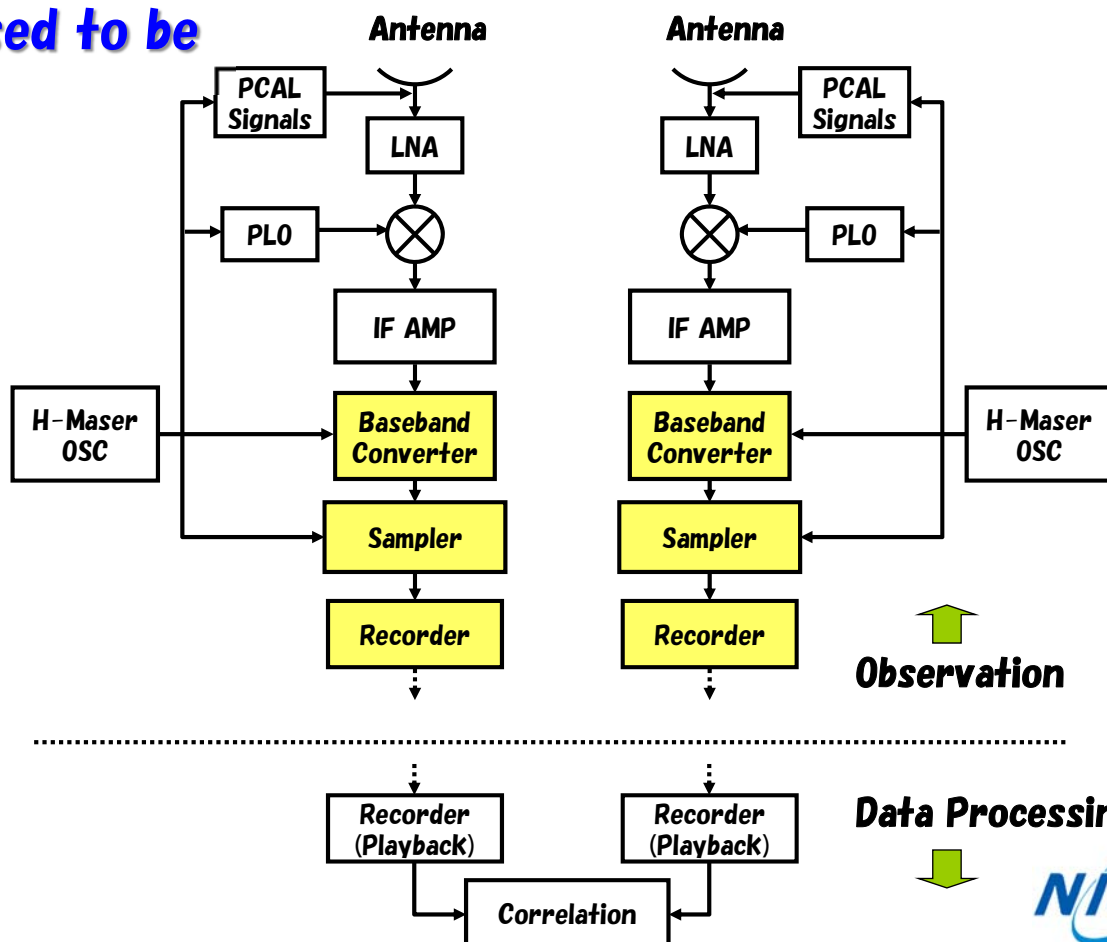
20-Jul-01 02:56:24 (JST)



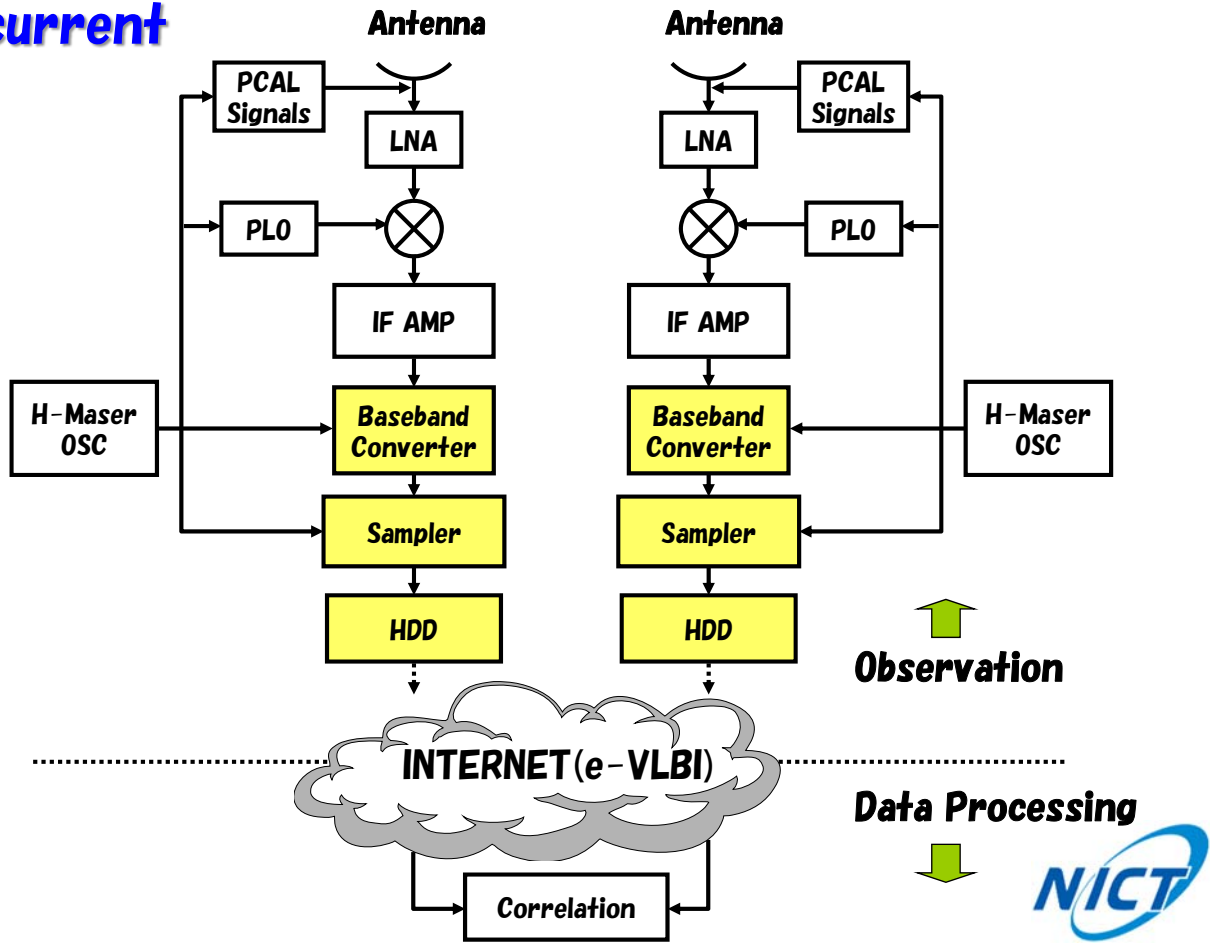
# Evolution of VLBI System



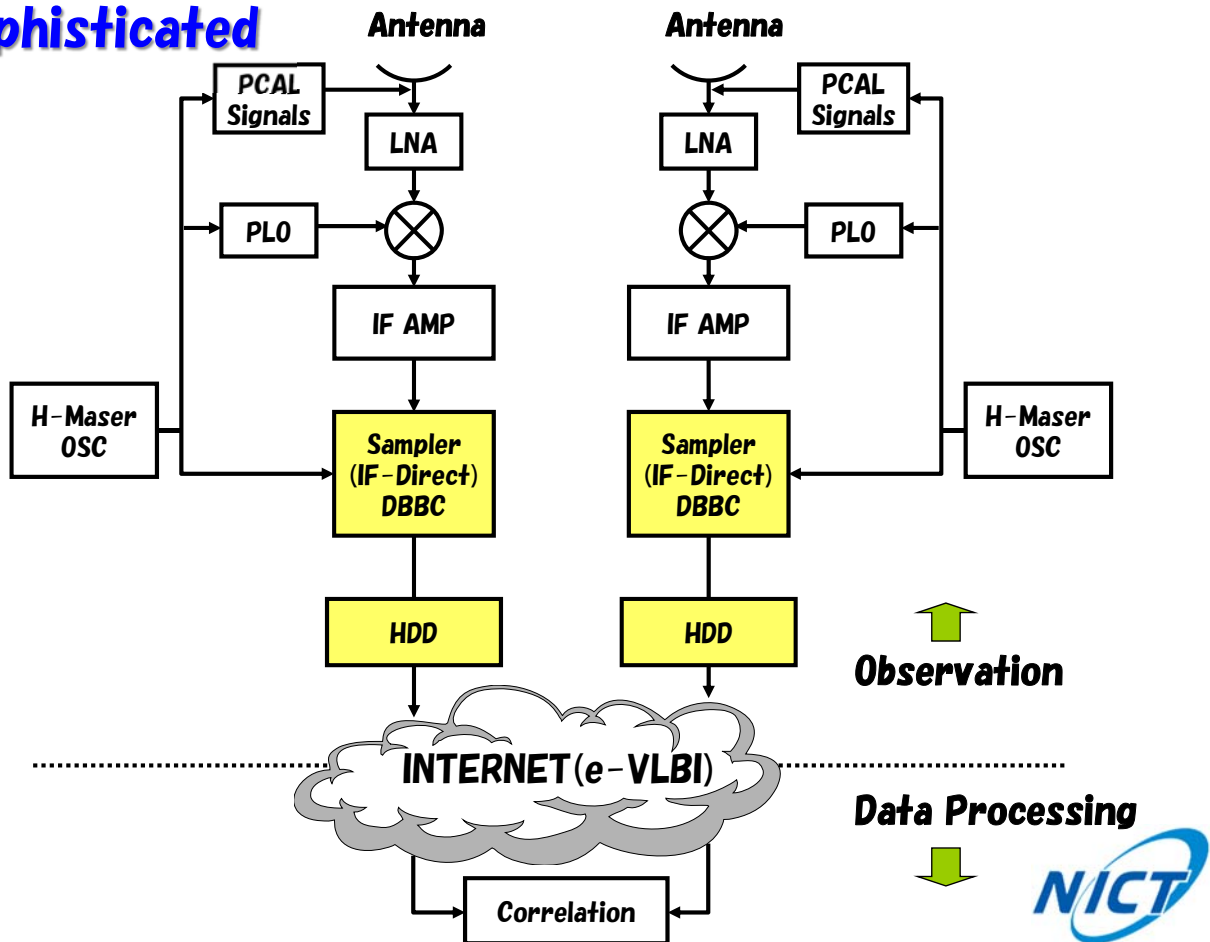
used to be



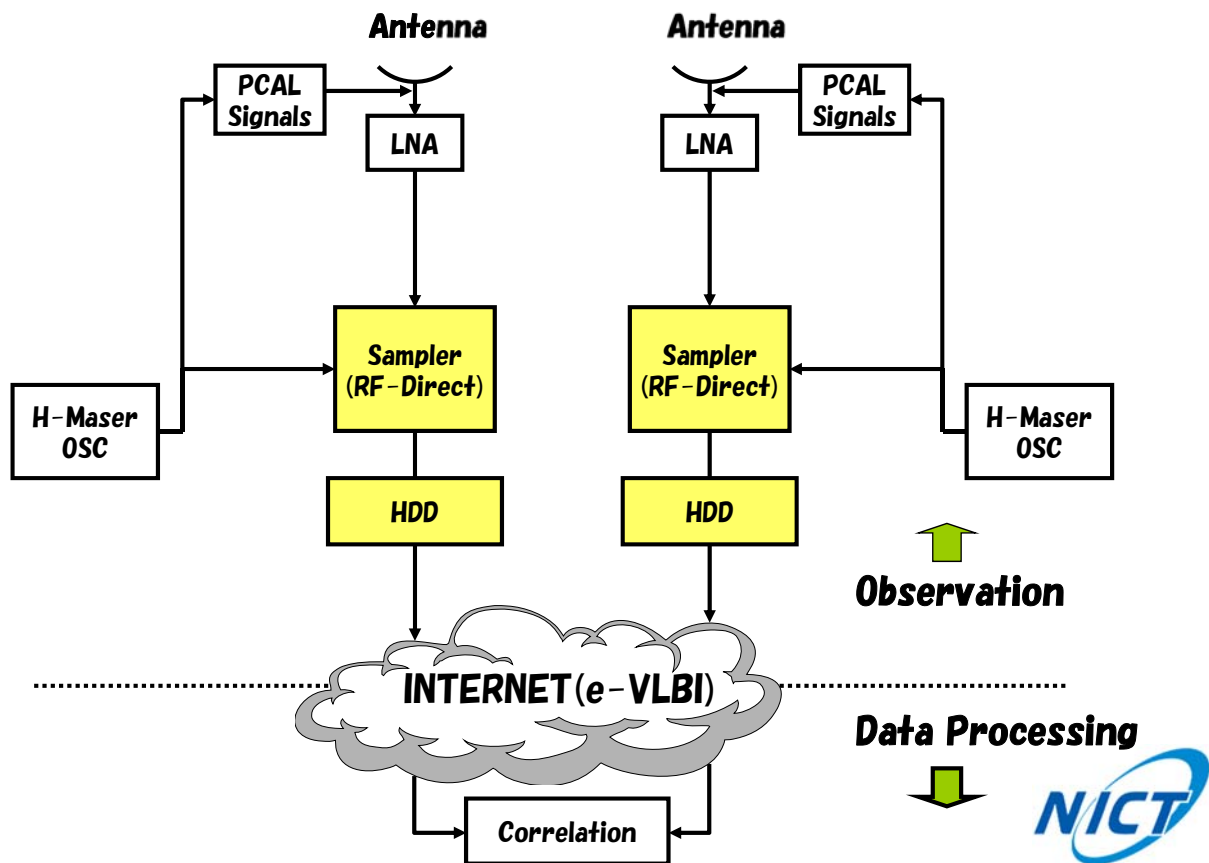
# current



# sophisticated

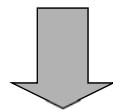


# more sophisticated RF direct sampling

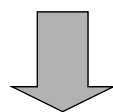


## Merits

**No use of analog frequency converter**



**Simple receiving system  
(minimum use of analog circuits)**



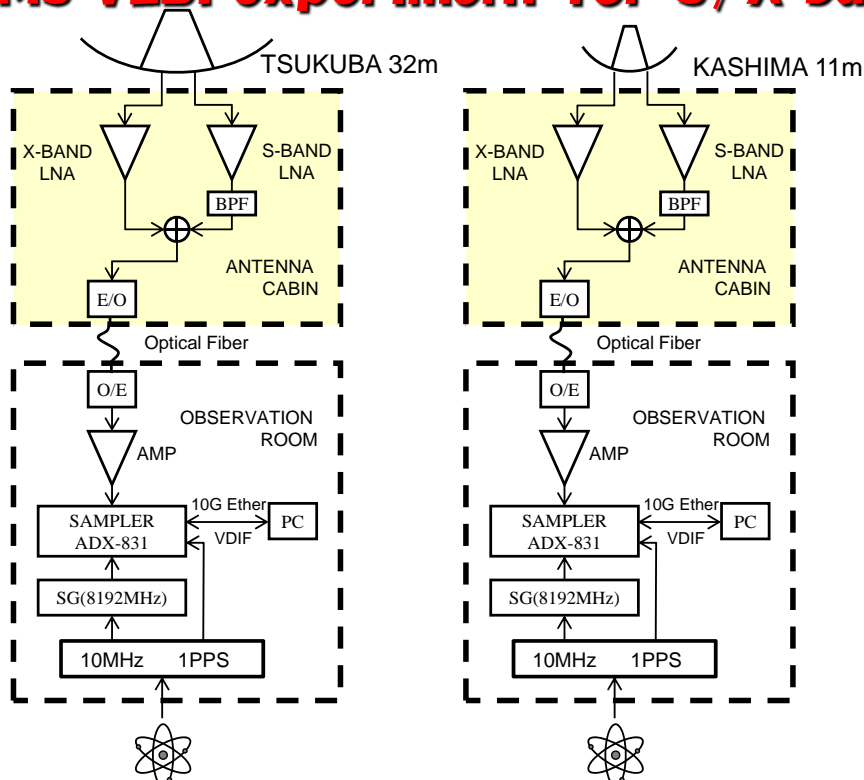
- **more stable and reliable**  
=> **accuracy improvement**
- **low cost system**

# Proof-of-Concept Experiment

## DSAMS: Direct Sampling Applied to Mixed Signals



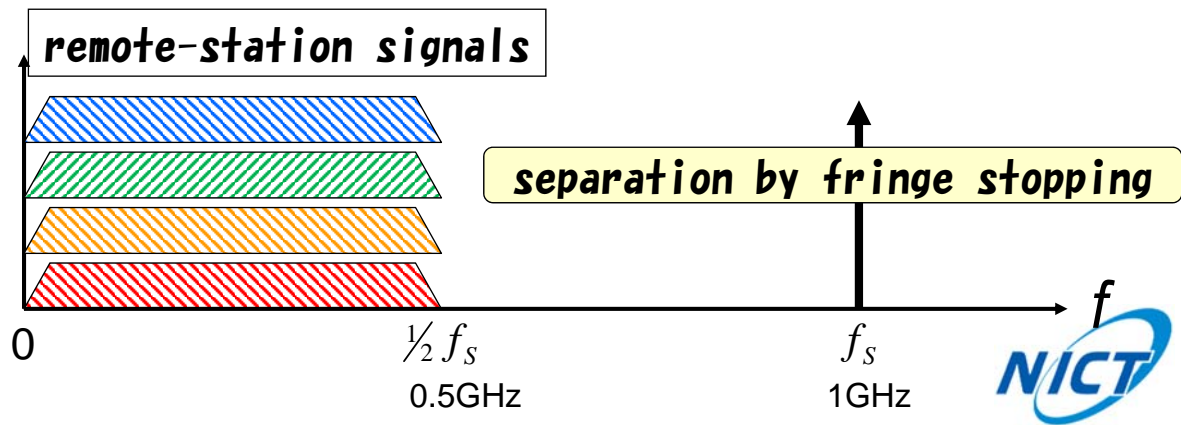
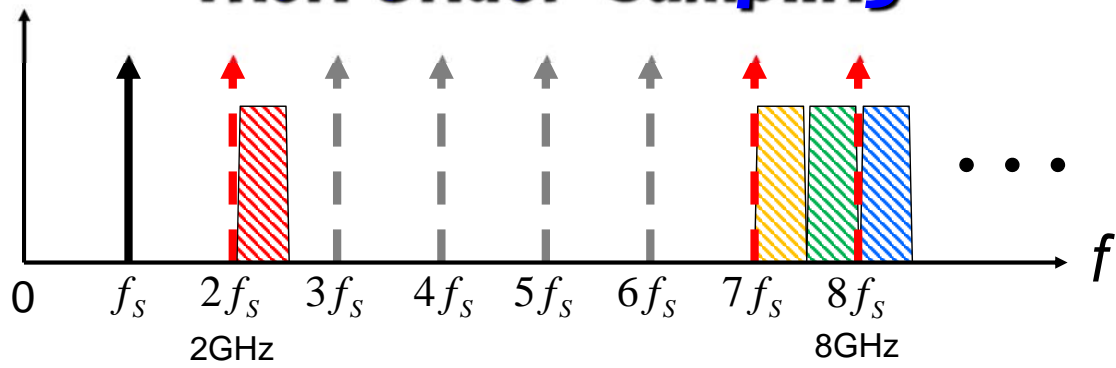
### Proof-of-Concept Experiment DSAMS VLBI experiment for S/X bands



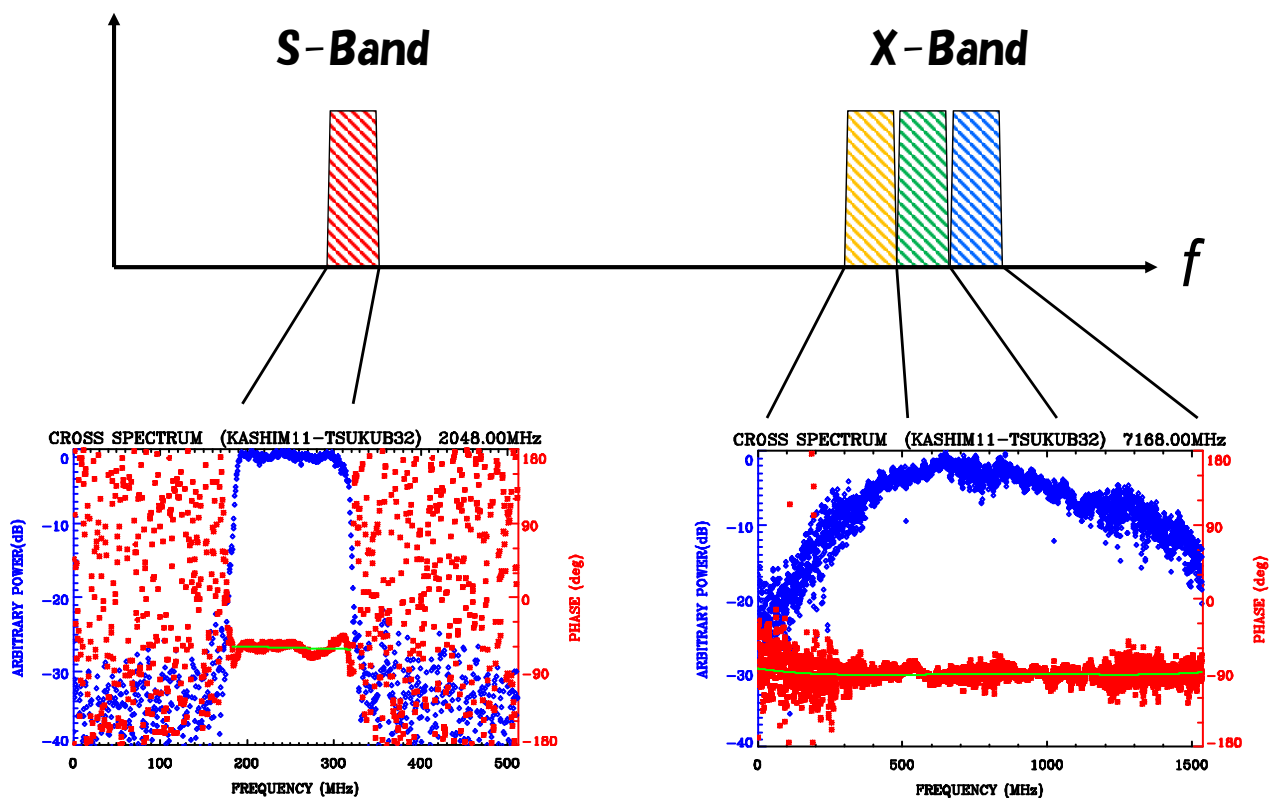
DSAMS: Direct Sampling Applied to Mixed Signals



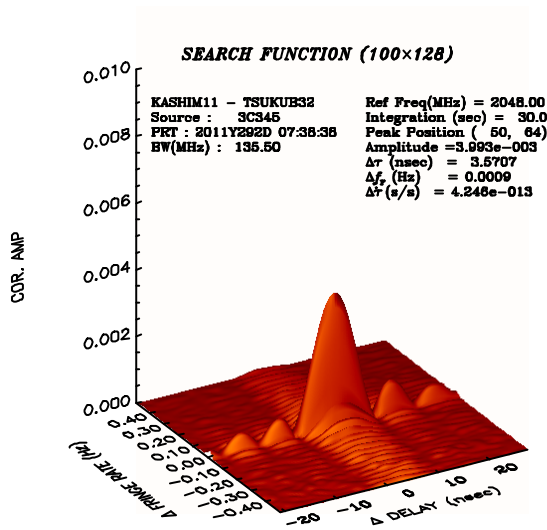
# Merging S and X bands at RF then Under Sampling



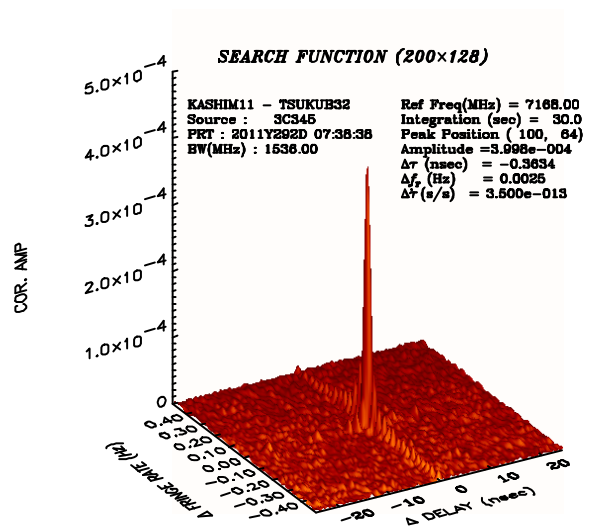
# Results of DSAMS VLBI Experiment



# DSAMS VLBI Experiment



S-Band



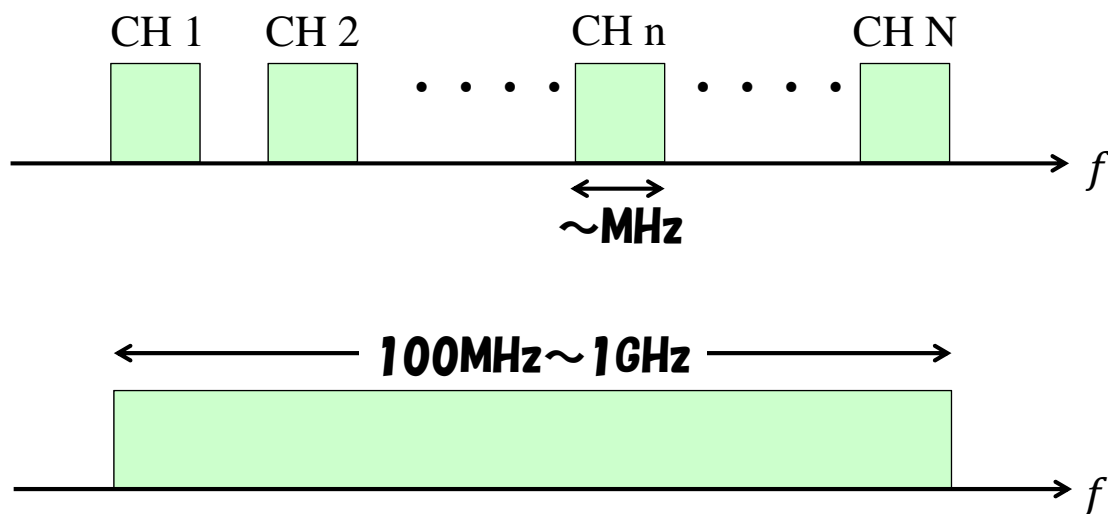
X-Band



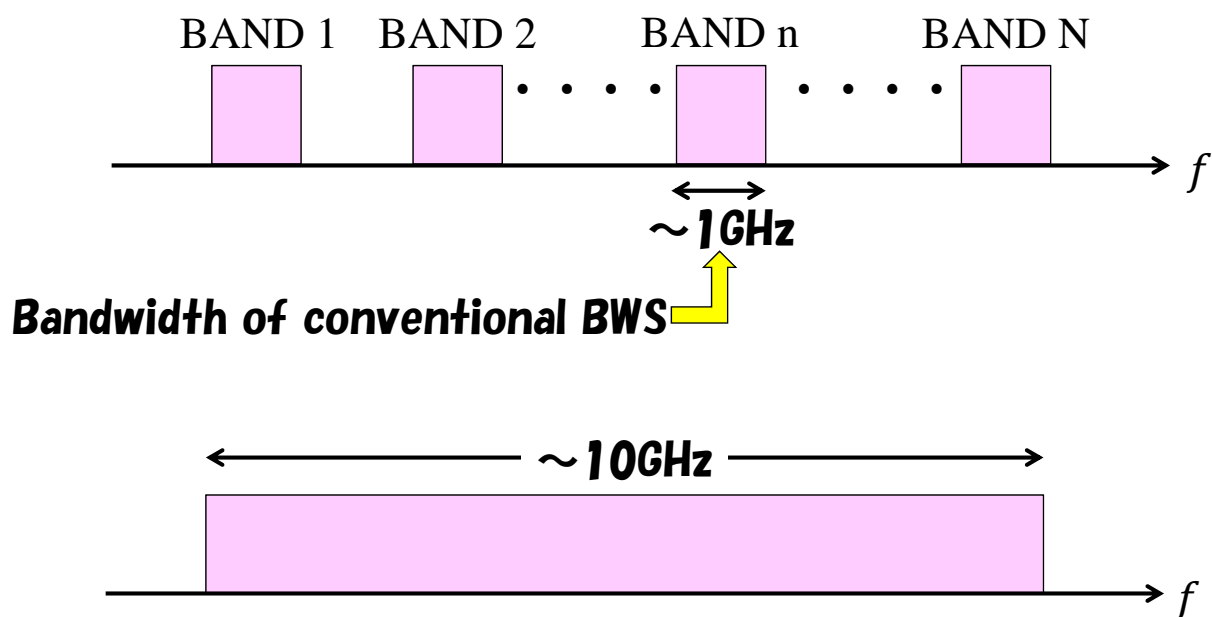
# Wideband Bandwidth Synthesis (WBWS)



# Conventional Bandwidth Synthesis



# Wideband Bandwidth Synthesis (WBWS)





# Search Function

## Conventional Bandwidth Synthesis

$$F(\Delta\tau, \Delta\dot{\tau}) = \left| \int_0^B \left\{ \int_0^T S(f, t) e^{-i2\pi f_0 \Delta\dot{\tau} t} dt \right\} e^{-i2\pi \Delta\tau f} df \right|$$



## Wideband Bandwidth Synthesis

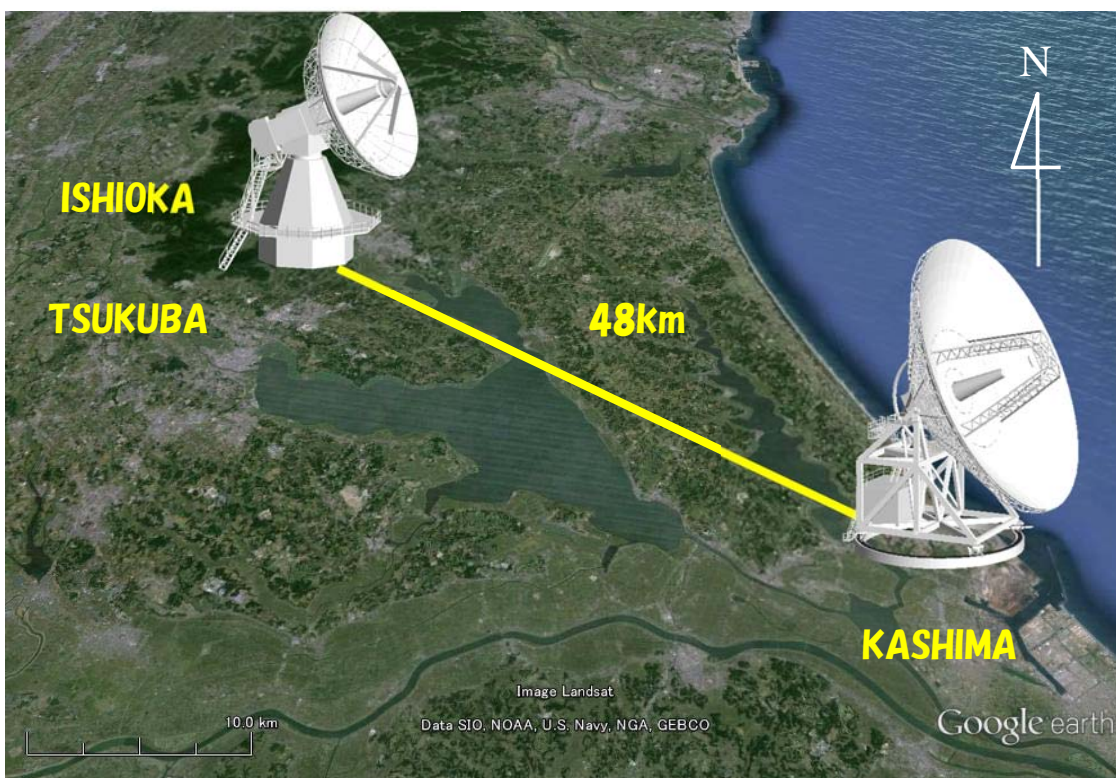
$$F(\Delta\tau, \Delta\dot{\tau}) = \left| \int_0^B \left\{ \int_0^T \boxed{S(f, t)} e^{-i2\pi(f_0+f)\Delta\dot{\tau} t} dt \right\} e^{-i2\pi \Delta\tau f} df \right|$$

**combined cross spectrum over all bands**

$f_0$  : reference RF frequency

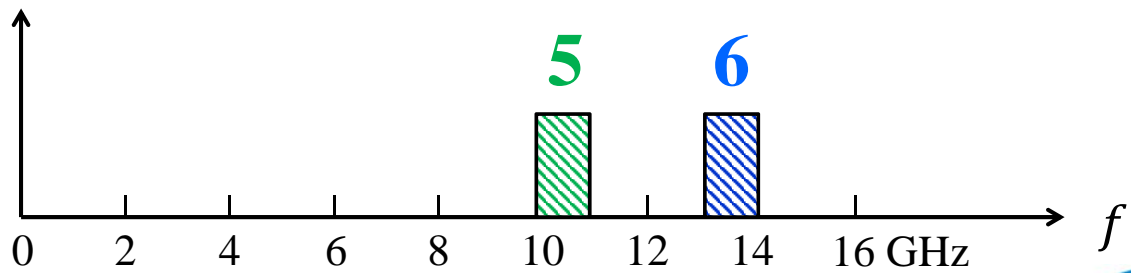
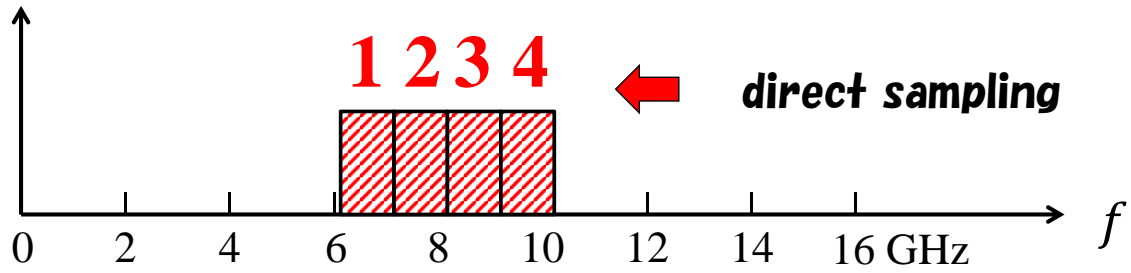


## Kashima – Ishioka baseline



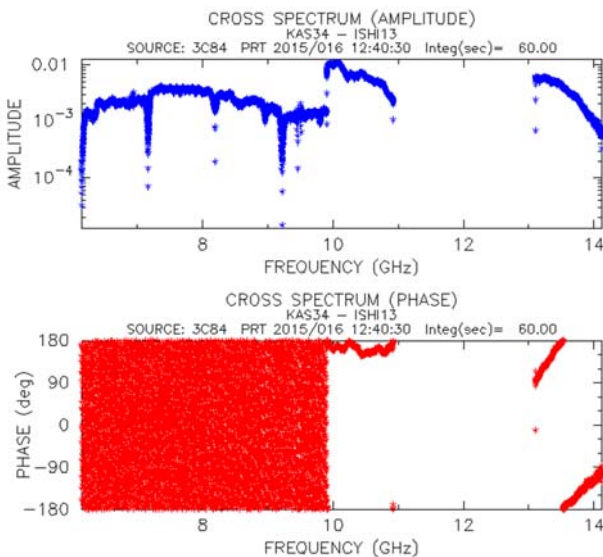
# Frequency Allocation

Bandwidth : 1024MHz

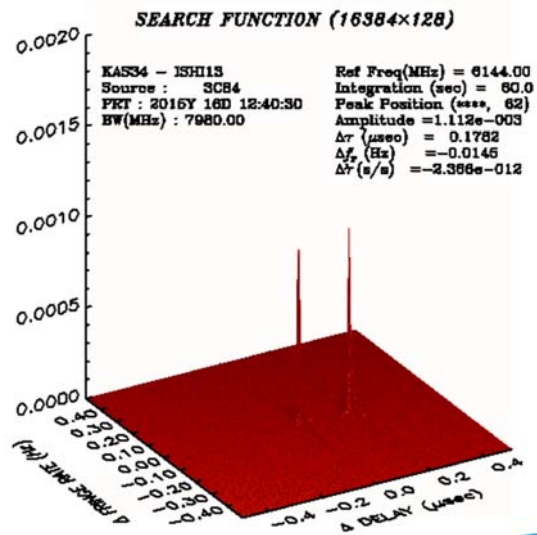


combine all bands without any correction

## cross spectrum

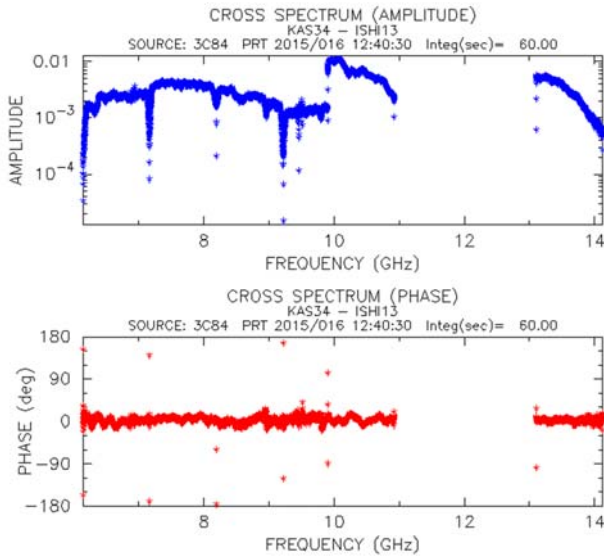


## search function

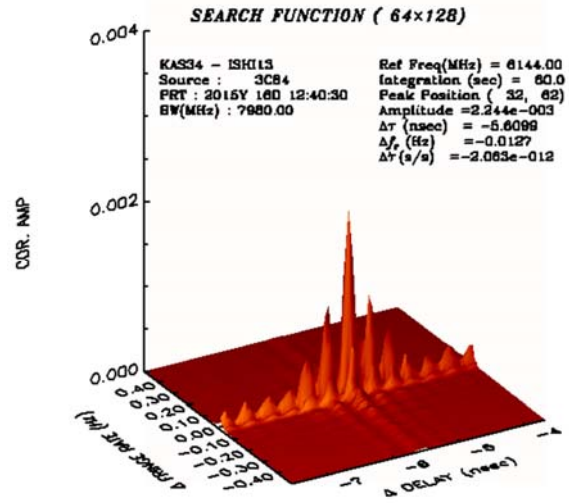


combine after band delay and phase corrections  
using reference scan data

### cross spectrum



### search function



theoretical error = 27fs

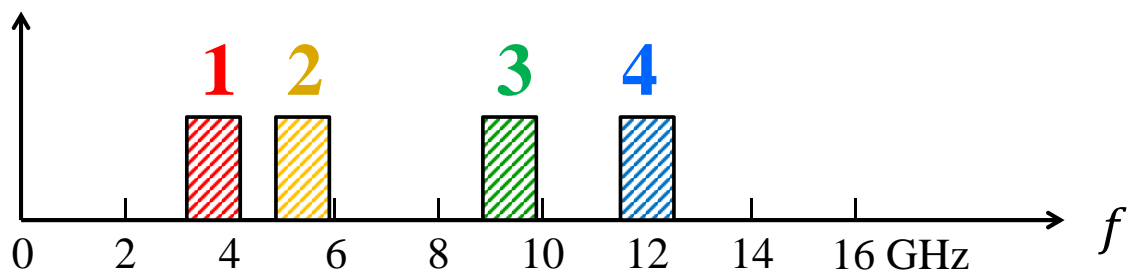
integration period = 60 sec



## another example

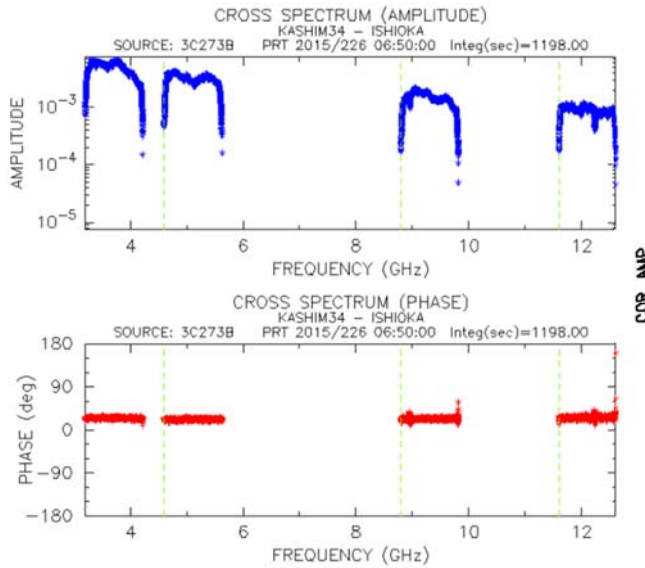
### Frequency Allocation

Bandwidth : 1024MHz

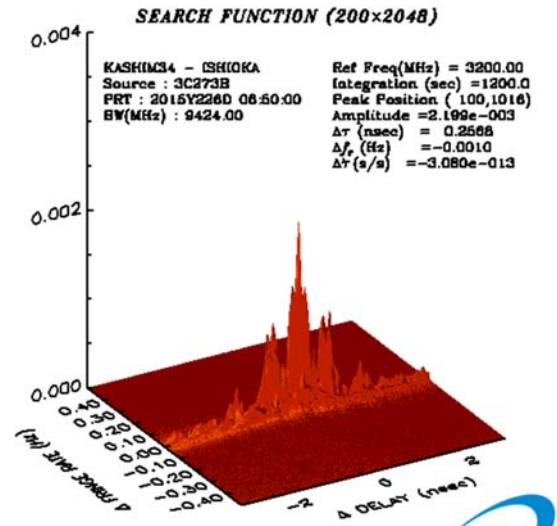


# after Wideband Bandwidth Synthesis

## cross spectrum



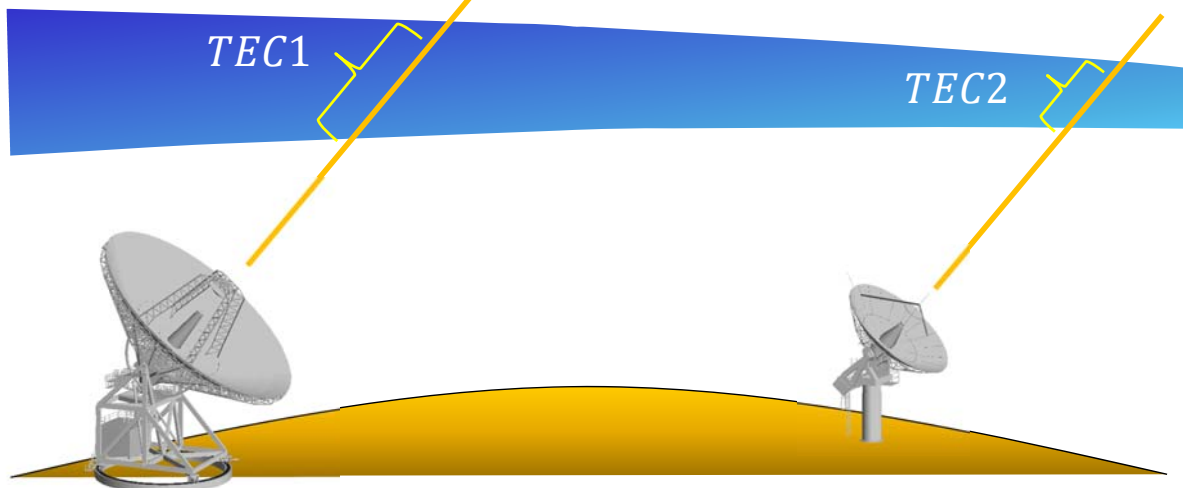
## search function



**integration period = 1200 sec**



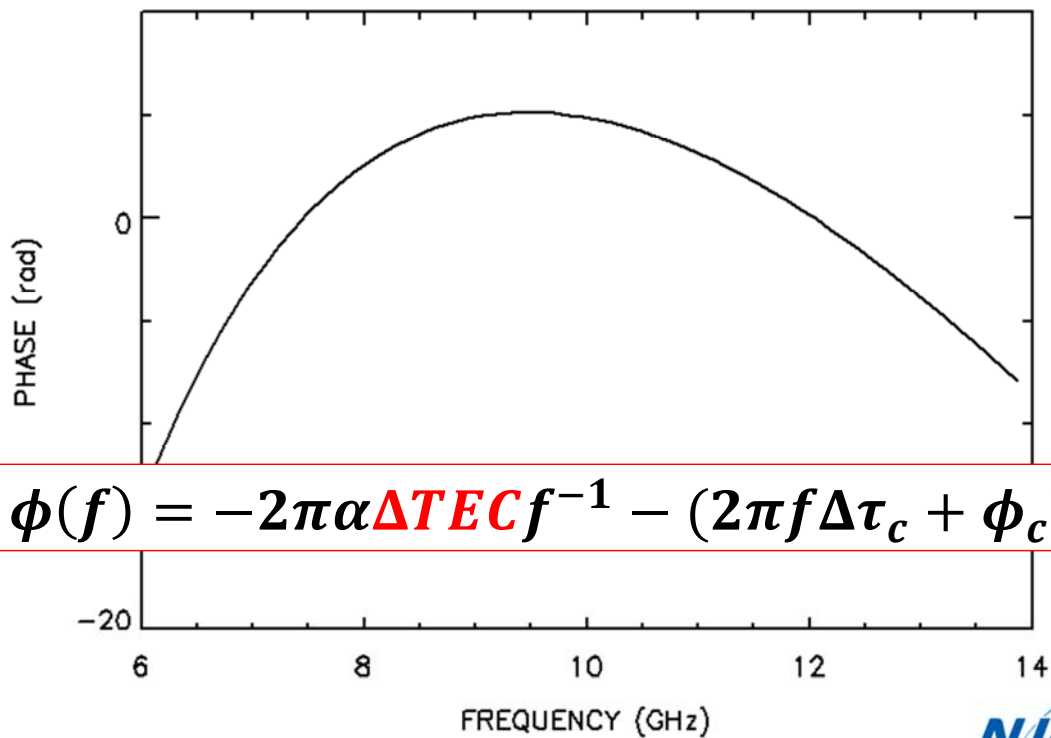
## Effect of Ionosphere



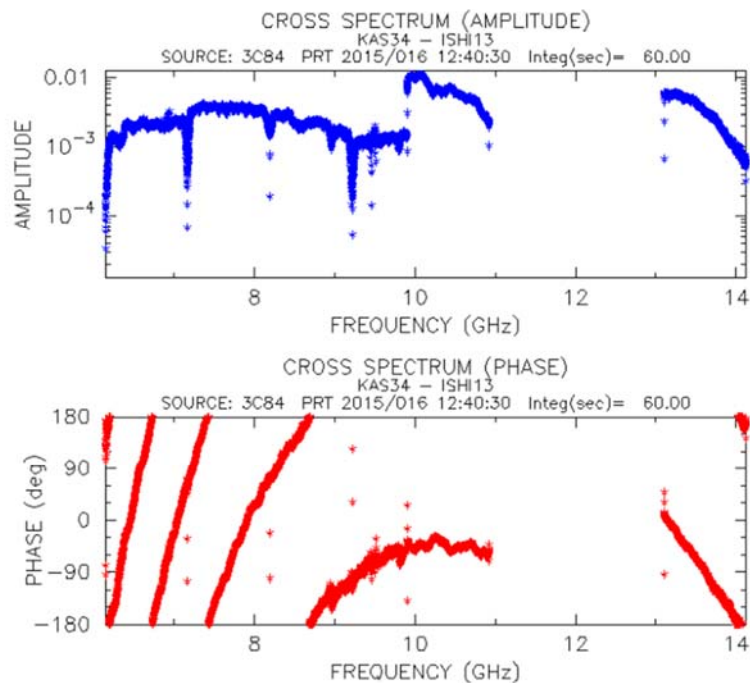
$$\Delta TEC = TEC1 - TEC2$$



# Example of Phase Spectrum after WBWS



## Simulated Cross Spectrum (after WBWS)

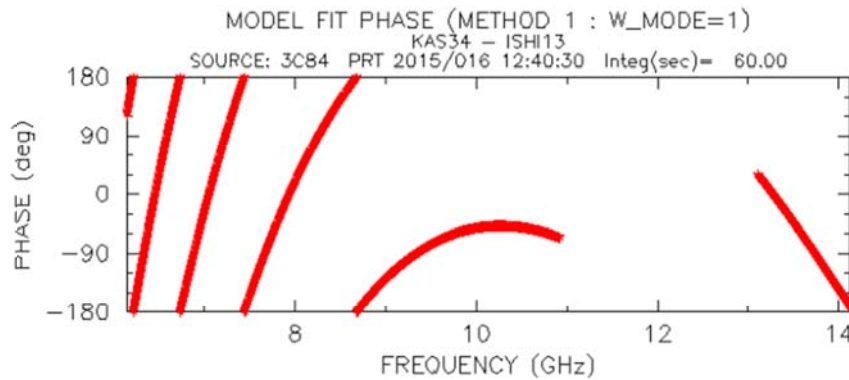


$\Delta TEC = +100 \text{ TECU}$

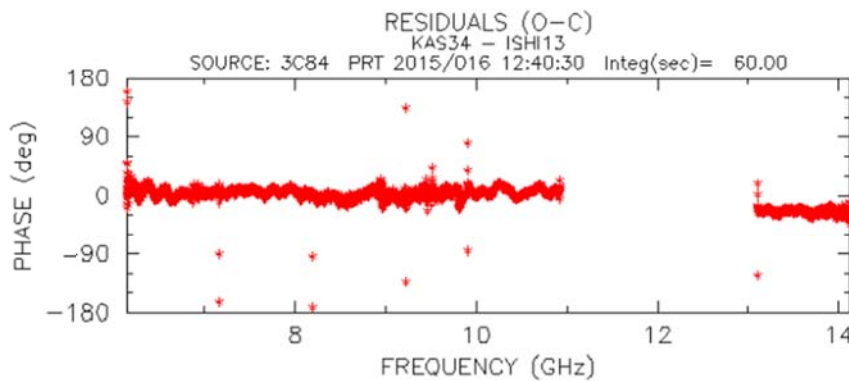


## Model phase after TEC estimation and residual phase

model  
phase



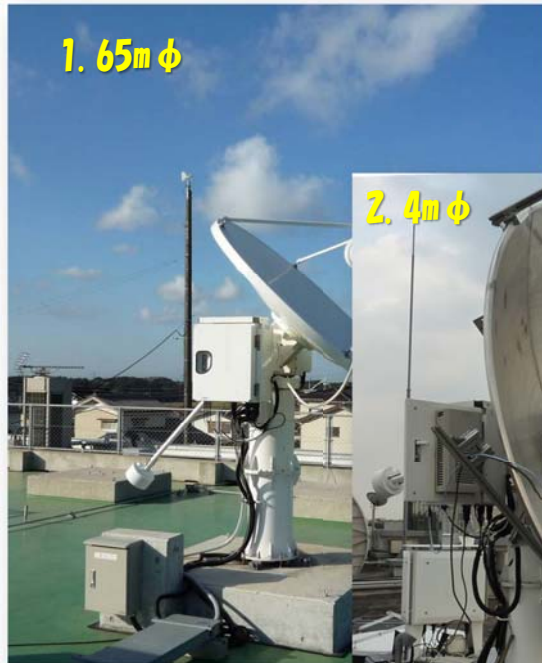
residual  
phase



# VLBI With a Small Antenna System



# MARBLE System



## Easy Installation (only by human power)



# **VGOS (<=VLBI2010)**

**defined by IVS**

## **VLBI Global Observing System**

**IVS: International VLBI Service  
for Geodesy & Astrometry**



## **VGOS GOAL**

- **1-mm position accuracy on global scales**
- **continuous measurements for time series of station positions and Earth orientation parameters**
- **turnaround time to initial geodetic results of less than 24 hours**





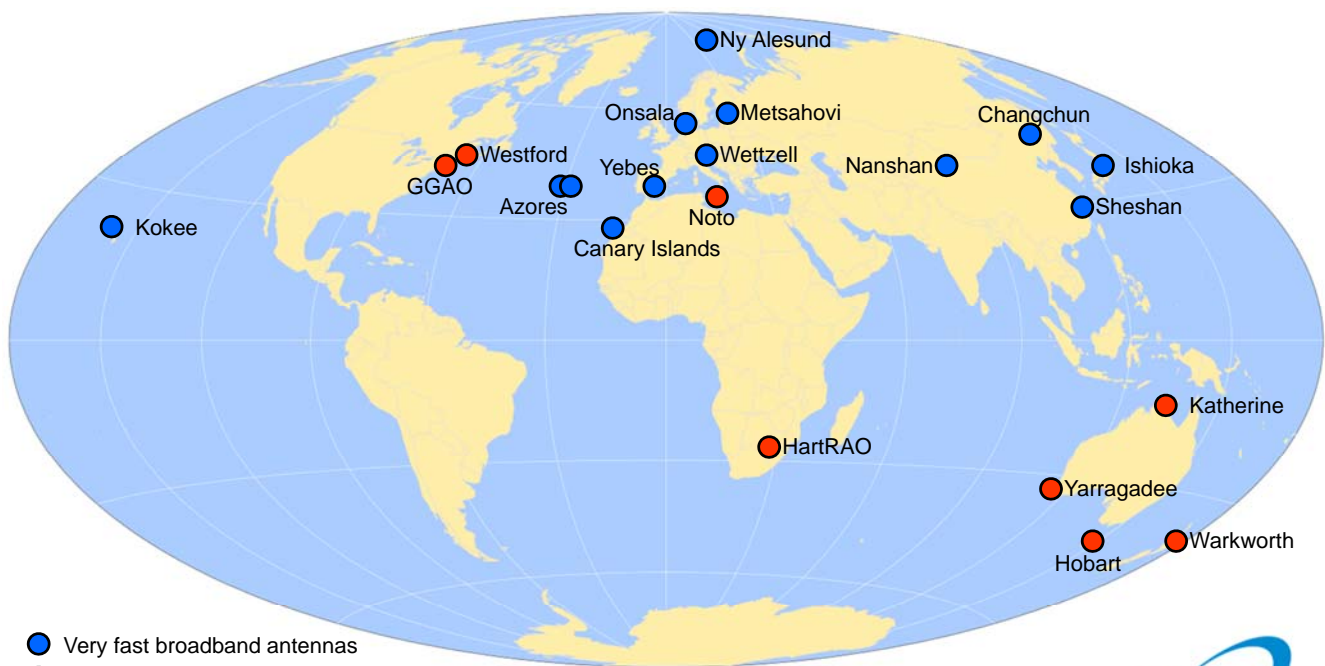
# Summary of VGOS Specifications

	Current	VGOS
Antenna Size	5 - 100 m dish	~ 12 m dish
Slew Speed	~0.3 - 3.3 deg/sec	≥ 12 deg/sec (single ant) ≥ 5 deg/sec (pair ant)
Sensitivity	200 - 15,000 SEFD	≤ 2,500 SEFD
Frequency Range	2 / 8	2 - 14 GHz
Polarization	RHCP	Dual Linear Polarization
Data Rate	128, 256 Mbps	8 - 16 Gbps future 32 Gbps
Data Transfer	Ship disks, some e-transfer	e-transfer, e-VLBI, some ships



## VGOS Network anticipated for 2017

Strong in the North Polar Region  
Weaker in the Americas and Pacific Region



- Very fast broadband antennas
- Fast and legacy broadband antennas

(after Petrachenko, EGU, Vienna, 2013)



# First VGOS Antenna in Japan

**Ishioka 13 m  
GSI**



## Outlook for the future

- **Wideband Bandwidth Synthesis (WBWS) on the inter-continental baseline to proof ionospheric correction**
- **Evaluate broadband system proposed in VGOS**
- **Continuous technology development for e-VLBI**